

Bharatiya Vidya Bhavan's



(Government Aided Autonomous Institute under Mumbai University) Andheri (W), Mumbai – 400058

COURSE CONTENTS

Sem. VII

B.Tech. (ELECTRICAL) ENGINEERING

Academic Year 2024-25

List of Courses

PC-BTE701	Electric Drives
PC-BTE702	Electric Drives Laboratory
PE-BTE702	Electrical Machine Design II
PE-BTE703	Design Management and Auditing of Electrical Systems
PE-BTE704	Digital Control Design
PE-BTE705	Restructuring and Deregulation of Power System
PE-BTE706	High Voltage Engineering
PE-BTE707	Power Electronics Applications in Power System
PE-BTE708	Computer Aided Power System Analysis
PE-BTE709	Electric Vehicle System Design
OE-BTE701	Computer Network
OE-BTE702	Engineering Economics
OE-BTE703	Embedded System
OE-BTE704	Internet of Things
PR-BTE701	Project Stage I
VA-BTE01/0	2 Value Added Courses

Electric Drives

	_	ERCUR DIVES	
Course Code		Course Name	
PC-B	PC-BTE701 Electric Drives		
<u> </u>	• •.		
Course pro	e-requisites	Power Electronics	
		Course Objectives	
The objecti	ves of this co		
	Understand	fundamentals of electric drives and their control through	l
	U	of electrical machines and power electronics	
		sics, dynamics, selection, braking and control of AC/DC	drives.
		plications of drives in industry	
4.	Understand	the selection of motor as per the torque-speed characteri	stics of load.
Upon augo	actul commis	Course Outcomes	
		tion of the course, students should be able to	
		indamental concept of electrical drives system.	
2.		ectrical drive for a particular	
	characteristi	and based on mechanical	
2			
3.	and solid sta	OC and AC motor using conventional te drives.	
		Course Content	
Module		Details	Hrs.
No.			
	Introductio		04
1	0	s of Electrical Drives, Parts of Electrical Drives,	
		Electrical Drives, Status of DC and AC Drives	08
	•	of Electrical Drives: tal torque equations, Speed torque conventions and	00
		rant operation, Equivalent values of Drive parameter,	
2	-	ent of moment of Inertia, Components of load torque,	
		l Classification of load torques, Calculation of Time	
		-Loss in transient operation, Steady state	
	and Liter 5		
		oad equalization	
	stability, L Selection o	f Motor Power Rating:	04
3	stability, L Selection o Thermal M	of Motor Power Rating: lodel of motor for heating and cooling, Classes of	04
3	stability, L Selection o Thermal M motor ratin	of Motor Power Rating: lodel of motor for heating and cooling, Classes of ag, Determination of motor rattling.	
3	stability, L Selection o Thermal M motor ratin Control of	of Motor Power Rating: lodel of motor for heating and cooling, Classes of ag, Determination of motor rattling. Electrical Drives:	04 04
3	stability, L Selection of Thermal M motor ratin Control of Modes of o	of Motor Power Rating: lodel of motor for heating and cooling, Classes of ag, Determination of motor rattling. Electrical Drives: operation, Speed control drive classification, Closed	
	stability, L Selection of Thermal M motor ratin Control of Modes of of loop control	of Motor Power Rating: lodel of motor for heating and cooling, Classes of ag, Determination of motor rattling. Electrical Drives: operation, Speed control drive classification, Closed ol of drives. Speed sensing, current sensing, Phase	
	stability, L Selection of Thermal M motor ratin Control of Modes of of loop control locked loop	of Motor Power Rating: lodel of motor for heating and cooling, Classes of ag, Determination of motor rattling. Electrical Drives: operation, Speed control drive classification, Closed ol of drives. Speed sensing, current sensing, Phase op control	04
	stability, L Selection of Thermal M motor ratin Control of Modes of of loop control locked loop DC Drives	of Motor Power Rating: lodel of motor for heating and cooling, Classes of ag, Determination of motor rattling. Electrical Drives: operation, Speed control drive classification, Closed ol of drives. Speed sensing, current sensing, Phase p control :	
4	stability, L Selection of Thermal M motor ratin Control of Modes of of loop control locked loop DC Drives Speed toro	of Motor Power Rating: lodel of motor for heating and cooling, Classes of ag, Determination of motor rattling. Electrical Drives: operation, Speed control drive classification, Closed of drives. Speed sensing, current sensing, Phase op control	04

	Speed Control (Armature voltage, Field flux, Armature resistance), Methods of Voltage control (Ward Leonard scheme, Controlled rectifiers, Controlled rectifier fed DC drives (separately excited only), Single phase fully-controlled rectifier, Single phase half- controlled rectifier, three phase fully-controlled rectifier, three phase half controlled rectifier, dual converter control, Chopper control (motoring and braking of separately excited and series motor)	
6	AC Drives: Induction motor drives, Review of speed-torque relations, Review of starting 6. methods, Braking (Regenerative, Plugging, AC/DC Dynamic braking), Speed control: Stator voltage control variable frequency control from voltage Source (V/F Control),Wound rotor induction motor control, rotor resistance control, Slip power recovery scheme, State Kramer and Scherbius drive, Vector control (elementary treatment only), Introduction to Synchronous Motor variable speed drive	08
7	Special Motor Drives: Stepper motor drives, Types, Torque v/s stepping rate characteristics, Drive circuits, Introduction to Brush- less DC drives, Introduction to Switched reluctance drives. Solar and Battery Drives, Recent trends in Electric Drives.	06

- 1. G. K. Dubey, "Power Semiconductor Controlled Drives", Prentice Hall..
- 2. R. Krishnan, "Electric Motor Drives: Modeling, Analysis and Control", Prentice Hall.

Reference Books

- 1. G. K. Dubey, "Fundamentals of Electrical Drives", CRC Press.
- 2. W. Leonhard, "Control of Electric Drives", Springer Science & Business Media.
- 3. Subrahmanyam V, Electrical Drives: Concepts and Applications TMH
- 4. Pillai S.K, A First course on Electrical Drives Wiley Eastern PH

Sr. No.	Examination	Module
1	T-I	1, 2
2	T-II	3,4, part of 5
3	End Sem	1 to 7

Electric Drives Laboratory

Course Code	Course Name
PC-BTE702	Electric Drives Laboratory

Course pre-requisites

Course Objectives

The objectives of this course are

- 1. Perform simulations of electrical drives
- 2. Perform experiments on Plugging. Braking of DC and Induction motors
- 3. Perform experiments to understand different types of electrical drives

Course Outcomes

Upon successful completion of the course, students should be able to

- 1. Simulate Electrical Drives
- 2. Understand braking and plugging of dc and induction motors.
- 3. Understand DC, induction and stepper motor drive

	Course Content	
Module No.	Details	Hrs.
1	Simulation of Electrical drives.	2
2	Simulation of starting of DC motor (soft start).	2
3	Dynamic braking of DC motor.	2
4	Plugging of DC motor/Plugging while lowering the load.	2
5	Regenerative braking of DC motor (by making V <eb) for="" high="" inertia="" load.<="" td=""><td>2</td></eb)>	2
6	DC or AC Dynamic braking of 3 phase induction motor.	2
7	Plugging of induction motor	2
8	Single phase full wave controlled DC motor drive.	2
9	Chopper Drive.	2
10	V/F control of Induction motor using PWM inverter	2
11	Measurement of moment of inertia by retardation test	2
12	Study of stepper motor drive	2
	Term Work	
	k shall comprise of Examination/ MCQ examination	
	k shall comprise of Examination/ MCQ examination	

Electrical Machine Design II

Course Code Course Name			
PE-B'	TE702	Electrical Machine Design II	
Course pre-requisites Electrical Machine design I			
		Course Objectives	
The objecti		e design of transformers, induction motors and synchron ion to computer aided design	ous machines
		Course Outcomes	
Upon succe	 Unders machin Unders magnet Unders basic d 	tion of the course, students should be able to tand the construction and performance characteristics of les. tand the various factors which influence the design: elect tic and thermal loading of electrical machines tand the principles of electrical machine design and carry esign of an ac machine. ftware tools to do design calculations Course Content	rical,
Module			
No.		Details	Hrs.
1	considerati – Choice loadings. Design of Circuit Rat	of Synchronous machine: Specification. Major ons in Synchronous machine design - Output Equation of specific electrical – Choice of specific magnetic Salient pole Machines: Main Dimensions. Short tio (SCR) – Effect of SCR on machine performance. Air gap. Shape of Pole Face.	04
2	Conductor Insulation. Harmonics Armature I	Design: Choice of number of slots – Turns per phase – section. Armature Windings – Coils and their Stator Slot Dimensions Stator Core. Elimination of . Armature parameters – Armature Resistance – Leakage Reactance. Estimation of Air gap length.	08
3	Height – D magnetic c Field Wind – Short Efficiency	Salient pole Rotor: Selection and Type of Pole – pole Damper Winding – Height of Pole Shoe – Mmf for the ircuit – Estimation of full load field mmf – Design of ling. Determination of d & q Synchronous reactances Circuit Characteristic. Estimation of Losses and - Temperature Rise.	08
4	-	urbo alternators: Main Dimensions. Length of Air gap esign -Rotor design	04
5	Computer Introductio	Application in Electrical Machine Design:	08

	Design (CAD) – Analysis Method - Synthesis Method -			
	Hybrid Method.			
	Optimization – General Procedure for Optimization – Variables			
	and Constraints – Problem formulation. Computer aided Design			
	of Transformer- Basic Aspects - Flowcharts for Transformer			
	design. Computer aided Design of Induction motor – Basic			
	Aspects – Flowcharts for Induction motor design.			
6	Introduction to FEM based machine design.	04		
7	Introduction to complex structures of modern machines-PMSMs,	06		
/	BLDCs, SRM and claw-pole machines.			
	Term Work			
Term worl	k shall comprise of			

- 1. Tutorials based on each module in the syllabus content
- 2. MCQ examination.

Text Books

- 1. A. K. Sawhney, "A Course in Electrical Machine Design", Dhanpat Rai and Sons, 1970.
- 2. S. K. Sen, "Principles of Electrical Machine Design with computer programs", Oxford and IBH Publishing, 2006.

Reference Books

1. M.G. Say, "Theory & Performance & Design of A.C. Machines", ELBS London

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	1 to 7

Design Management and Auditing of Electrical Systems

Course Code	Course Name
PC-BTE703	Design Management and Auditing of Electrical Systems

Course pre-requisites

	Course Objectives		
The objectiv	ves of this course are		
1. Introduction to types of electrical projects and electrical systems, energy			
conservation law, basics of tendering and estimation.			
2.	 Discussion of basic concepts of design of electrical systems 		
	2. Discussion of basic concepts of design of electrical systems like power distribution, switchgear protection and auxiliary		
	system.		
3.	Learning of management and auditing procedure of electrical system	ıc	
	Understanding renewable-energy and green building concepts from a		
т.	perspective.	lesign	
	Course Outcomes		
Upon succe	ssful completion of the course, students should be able to		
1.	Work as a team leader or a member in multidisciplinary projects in		
	the role of electrical engineer.		
2.	Identify the requirement of the project and design electrical		
	systems accordingly as per IS standards.		
3.	Apply energy efficient ways in design and selection of electrical cor	nponents.	
4.	Realize role of renewable-energy and green building concepts in ele	ctrical design.	
	Course Content	U	
Module	Details	Hrs.	
No.		1175.	
	Introduction:	04	
	Types of electrical projects, Types of electrical systems, Review		
1	of components of electrical system, Different plans/drawing in		
	electrical system design, Single line diagram in detail,		
	Introduction to Energy Conservation Act 2001		
	Design of Power Distribution System:	06	
	Different types of distribution systems and selection criteria,		
	Electrical load: Size, LF, DF, future estimates, Substation		
2	equipment options, Design consideration in: Transformer		
	selection, sizing and specifications. IS standards applicable in		
	above designs. (Substation "LV" Design)		
	Design of Switchgear Protection and Auxiliary System:	06	
	Selection of HT/LT switchgears, Metering, Switchboards and		
	MCC, Protection systems, cables: selection and sizing, cable		
3	installation and management systems, Basics of selection of		
	emergency/backup supplies.		
	UPS, DG set, Batteries, Preliminary design of interior lighting		
	system, IS standards applicable in above designs.		
	system, is standards applicable in above designs.		
4	Tendering Process:	04	

	financial analysis techniques: Time value of money, Simple	
	payback, IRR.	
	Monitoring and Management of Electrical Systems:	10
	Energy monitoring and Targeting: Defining monitoring and	
	targeting,	
	Elements of monitoring and targeting, Energy analysis	
	techniques for energy optimization. Electricity billing, Electrical	
	load management and maximum demand control, Power factor	
	improvement and its benefit, Selection and location of capacitors,	
5	Performance assessment of PF capacitors, Distribution and	
5	transformer losses, Introduction to Energy Efficient Technologies	
	in Electrical systems: Maximum Demand controllers, Automatic	
	Power factor controllers, Energy Efficient motors, Soft starters,	
	Variable speed drives,	
	Energy Efficient Transformers, Electronic ballast, Occupancy	
	sensors, Energy efficient lighting controls, Energy saving	
	potential of each technology. Energy Management System (EMS)	
	and Building Management System (BMS) systems	
	Energy Audit:	08
	Definition, Energy audit-need, types of Energy audit, Energy	
	management (audit) approach- understanding energy costs,	
	Bench marking, Energy performance, Matching energy use to	
	requirement, Maximizing system efficiencies, Optimizing the	
	input energy requirements, Fuel and energy substitution, Energy	
6	audit instruments: Audit of installations comprising following	
	with respect to their electrical energy usage: Electric Motors,	
	HVAC systems, Fan and blower systems, Compressed air	
	systems pump, DG sets, Lighting installations etc.	
	Evaluation of energy conservation opportunities, Energy	
	conservation in buildings, Economic and non-economic aspects of	
	energy conservation in electrical systems	
	Use of Renewable and Green Building Concept:	04
7	Impact of renewable energy sources in electrical system design.	
	Concept	
	of Green Building and its accreditation.	
	Term Work	
	rk shall comprise of	
1		
2	. MCQ examination.	

Text Books

Reference Books

- 1. Handbook of Electrical Installation Practice. , By Geoffery Stokes, Wiley Blackwell
- 2. Designing with light: Lighting Handbook., By Anil Valia, Lighting System
- 3. Energy Management Handbook. By W.C. Turner, JohnWiley and Sons

4.	Handbook on Energy Audits and Management. edited by Amit Kumar
	Tyagi, Tata Energy Research Institute (TERI).
5.	Electrical Design: Estimating and Costing, by K. B. Raina and S. K.
	Bhattacharya, New Age International Publishers
6.	Energy Auditing Made Simple, By P. Balasubramanian, Seperation Engineers (P) Limited
7.	Energy Management Principles, By C.B.Smith, Pergamon Press
8.	Energy Conservation Guidebook, Dale R. Patrick, Stephen Fardo,
	Ray E. Richardson, Fairmont Press
9.	Handbook of Energy Audits., By Albert Thumann, William J. Younger,
	Terry Niehus, CRC Press

Sr. No.	Examination	Module
1	T-I	1, 2, Part of 3
2	T-II	Part of 3, 4, Part of 5
3	End Sem	1 to 7

Digital Control Design

		Digital Control Design	
Course Code Course Name			
PE-B7	ГЕ704	Digital Control Design	
Course pre-requisites Control System, Control System		Control System, Control System Design, Signals and	l Systems
		Course Objectives	
The objecti	ves of this co	<u> </u>	
1.		ete representation of LTI systems.	
2. Analyze stability of open loop and closed loop discrete-time systems.			
3. Design and analyze digital controllers.			
4.	Design state	feedback and output feedback controllers	
TT	<u> </u>	Course Outcomes	
-	-	tion of the course, students should be able to	
1.		ete representation of LTI systems.	
2. 3.		bility of open loop and closed loop discrete-time systems. analyze digital controllers.	
3. 4.	-	feedback and output feedback controllers.	
4.	Design state	Course Content	
Module			
No.		Details	Hrs.
		epresentation of Continuous Systems	06
		Digital Control Systems. Discrete representation of	
1		systems. Sample and hold circuit. Mathematical	
1		of sample and	
		t. Effects of Sampling and Quantization. Choice of	
		requency. ZOH equivalent, state space system	07
		ystem Analysis m and Inverse Z Transform for analyzing discrete	06
		ns. Pulse Transfer function. Pulse transfer function of	
2		b systems. Mapping from s-plane to z plane. Solution	
	of Discrete		
		ime response of discrete time system.	
		f Discrete Time System	04
	Stability ar	alysis by Jury test. Stability analysis using bilinear	
3	transforma	tion. Design of digital control system with dead beat	
	response.		
		sues with dead beat response design	
,	-	e Approach for discrete time systems	05
4	-	e models of discrete systems, State space analysis.	
	Lyapunov		05
	1	e Approach for discrete time systems	05
5		ility, reach-ability, Reconstructibility and observability affect of pole zero cancellation on the controllability &	
	observabili	-	
-		Digital Control System	08
6	•	ot for controller design, Design of Discrete PID	

	Controller, Design of discrete state feedback controller. Design of set point tracker. Design of Discrete Observer for LTI System. Design of Discrete compensator	
7	Discrete output feedback control Design of discrete output feedback control. Fast output sampling (FOS) and periodic output feedback controller design for discrete time systems.	08
Term Work		
Term work shall comprise of		
1. Tutorials		

2. MCQ examination.

Text Books	
1. M. Gopal, "Digital Control Engineering", Wiley Eastern, 1988.	
Reference Books	
1. K. Ogata, "Digital Control Engineering", Prentice Hall, Englewood Cliffs, 1995.	

- 2. G. F. Franklin, J. D. Powell and M. L. Workman, "Digital
 - Control of Dynamic Systems", Addison-Wesley, 1998.
- 3. B.C. Kuo, "Digital Control System", Holt, Rinehart and Winston, 1980.

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4,5
3	End Sem	1 to 7

Restructuring and Deregulation of Power System

Course Code	Course Name
OE-BTE705	Restructuring and Deregulation of Power System
Course pre-requisites	Power system-I and power system –II

Course Objectives

The objectives of this course are

- 1. To differentiate between vertically integrated and deregulated power system.
- 2. Challenges faced in operating restructured power system with reliability, security and economic efficiency.
- 3. Reforms adopted by developing country like India

Course Outcomes

Upon successful completion of the course, students should be able to

- 1. Identify different electrical market designs.
- 2. Understand fundamentals of micro economics.
- 3. Determine the suitable pricing method for centralised and decentralised trading.
- 4. Understand ancillary service and congestion management requirement of restructured power system

	Course Content	
Module No.	Details	Hrs.
	Introduction of restructured power system.	6
	• Reasons for restructuring and deregulation of power system	
1	Entities involved	
	Different model of competition	
	Electrical market vis-à- vis market of commodities	
	Fundamentals of micro economics	8
	Consumer behaviour	
	Supplier behaviour	
2	Market equilibrium	
-	Various cost of production	
	• Long term and short-term cost	
	• Types of markets	
	Markets with imperfection competition	
	Introduction to optimization	6
	Linear optimisation	
	• Convexity	
3	• Duality	
	KKT condition	
	Lagrange multiplier	
	Optimal dispatch of generation	
	Optimal Power Flow and Congestion Management.	8
4	• Optimal power flow – AC and DC formulation	
4	Spot Pricing	
	• Decentralised trading over the transmission network.	

	• Centralised trading over the transmission network.	
	Participating in markets for electrical energy	4
5	Consumer's perspective	
5	Producer's perspective	
	System security and ancillary service	5
	Ancillary service needs	
6	Obtaining ancillary service	
	Buying ancillary service	
	Selling ancillary service	
	Reforms in Indian Power Sector	5
	• Frame work of Indian power sector	
	• Electricity act 2003 and amendments	
7	Transmission system cost allocation	
	• Power exchanges – Day ahead market, real-time market	
	Deviation settlement mechanism	
	Ongoing and future developments	
	Term Work	
erm w	ork shall comprise of	
1	. Tutorials	
2	. MCQ examination	

Text Books

- 1. Daniel Krischen and Goran Strbac, "Fundamental of Power System Economics", John Wiley and Sons Ltd ,2004.
- 2. Sally Hunt, "Making Competition Work in Electricity", John Wiley and Sons, Inc., 2002

Reference Books

1. Steven Stoft , "Power System Economics: Designing Markets for Electricity", Wiley-IEEE Press, 2002.

Sr. No.	Examination	Module
1	T-I	1, part of 2
2	T-II	Part of 2,3,4
3	End Sem	1 to 7

High Voltage Engineering

Cours	e Code Course Name	
PE-B'	TE706 High Voltage Engineering	
Course pro	e-requisites	
The objecti	Course Objectives	
The objecti	ves of this course are 1. Discuss breakdown in gases, solid and liquid insulating material	
	 Introduce generation and measurements of high voltages. 	
	3. Discuss lightening and switching over voltages	
	4. Discuss high voltage testing	
	Course Outcomes	
	ssful completion of the course, students should be able to	
1.	Understand the basic physics related to various breakdown	
2	processes in solid, liquid and gaseous insulating materials. Knowledge of generation and measurement of D. C., A.C., & Impuls	e voltages
3.	Knowledge of tests on H. V. equipment and on insulating	e vonages.
	materials, as per the standards.	
4.	Knowledge of how over-voltages arise in a power system, and prot	ection against
	these over-voltages Course Content	
Module		
No.	Details	Hrs.
	Breakdown in Gases	08
	Ionization processes and de-ionization processes, Types of Discharge,	
1	Gases as insulating materials, Breakdown in Uniform gap, non-	
	uniform gaps, Townsend''s theory, Streamer mechanism,	
	Corona discharge	
	Breakdown in liquid and solid Insulating materials	07
	Breakdown in pure and commercial liquids, Solid dielectrics and	
2	composite dielectrics, intrinsic breakdown, electromechanical breakdown and thermal breakdown, Partial discharge,	
	applications of insulating	
	applications of insulating materials.	
	applications of insulating materials. Generation of High Voltages	07
3	applications of insulating materials. Generation of High Voltages Generation of high voltages, generation of high D. C. and A.C.	07
3	applications of insulating materials. Generation of High Voltages Generation of high voltages, generation of high D. C. and A.C. voltages, generation of impulse voltages, generation of impulse	07
3	applications of insulating materials. Generation of High Voltages Generation of high voltages, generation of high D. C. and A.C.	07
3	applications of insulating materials. Generation of High Voltages Generation of high voltages, generation of high D. C. and A.C. voltages, generation of impulse voltages, generation of impulse currents, tripping and control of impulse generators Measurements of High Voltages and Currents Peak voltage, impulse voltage and high direct current	
3	applications of insulating materials. Generation of High Voltages Generation of high voltages, generation of high D. C. and A.C. voltages, generation of impulse voltages, generation of impulse currents, tripping and control of impulse generators Measurements of High Voltages and Currents Peak voltage, impulse voltage and high direct current measurement method, cathode ray oscillographs for impulse	
	applications of insulating materials. Generation of High Voltages Generation of high voltages, generation of high D. C. and A.C. voltages, generation of impulse voltages, generation of impulse currents, tripping and control of impulse generators Measurements of High Voltages and Currents Peak voltage, impulse voltage and high direct current measurement method, cathode ray oscillographs for impulse voltage and current measurement, measurement of dielectric	
	applications of insulating materials. Generation of High Voltages Generation of high voltages, generation of high D. C. and A.C. voltages, generation of impulse voltages, generation of impulse currents, tripping and control of impulse generators Measurements of High Voltages and Currents Peak voltage, impulse voltage and high direct current measurement method, cathode ray oscillographs for impulse	

	Lightning Surges. Switching over voltages, Protection against over-voltages, Surge diverters, Surge modifiers.	
6	 High Voltage Testing of Electrical Apparatus and High Voltage Laboratories Various standards for HV Testing of electrical apparatus, IS, IEC standards, Testing of insulators and bushings, testing of isolators and circuit breakers, testing of cables, power transformers and some high voltage equipment, High voltage laboratory layout, indoor and outdoor laboratories, testing facility requirements, safety precautions in H. V. Labs. 	06
	Term Work	
Term work shall comprise of		
1.	. Tutorials	

2. MCQ examination

Text Books

- 1. M. S. Naidu and V. Kamaraju, "High Voltage Engineering", McGraw HillEducation, 2013.
- 2. C. L. Wadhwa, "High Voltage Engineering", New Age International Publishers, 2007.

Reference Books

- D. V. Razevig (Translated by Dr. M. P. Chourasia), "High VoltageEngineering Fundamentals", Khanna Publishers, 1993.
- 2. E. Kuffel, W. S. Zaengl and J. Kuffel, "High Voltage EngineeringFundamentals", Newnes Publication, 2000.
- 3. R. Arora and W. Mosch "High Voltage and Electrical Insulation Engineering", John Wiley & Sons, 2011.
- 4. Various IS standards for HV Laboratory Techniques and Testing

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	01-06

Power Electronics Applications in Power System

	Tower Electronics Applications in Fower 5	J
e Code	Course Name	
ТЕ707	Power Electronics Applications in Power	r System
Course pre-requisites Power Electronics Power System		
	Course Objectives	
	burse are	
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10 study the	*	
essful comple		
		rmance
		ed technology
	Course Content	
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	E-requisites ves of this co To study the improves the Introduction Discuss read using Voltag To study the essful comple 1. Understan 2. Able to an 3. Able to cr Introduction Brief discus source inv series and voltage pro load compu- using pass passive ele Use of VS Synchrono Various PV vector PW Expression component Shunt Con Introduction reactor (T capacitor to switched so capacitor	e Code Course Name TE707 Power Electronics Applications in Power e-requisites Power Electronics Power System e-requisites Power System Components Power System ves of this course are To study the operation of power system components that improves the power system performance. Introduction of series & shunt compensation for transmission lines. Discuss reactive power support & elimination of harmonics using Voltage Source Inverters. To study the operation & control of HVDC transmission system. Course Outcomes essful completion of the course, students should be able to 1. Understand the various methods of improving power system perfor 2. Able to analyze the existing system for performance improvement 3. Able to create the system performance improvement using advance

	regulator (PAR), Multi-function FACTS controller, Unified power flow controller (UPFC), control capabilities of UPFC,	
5	HVDC: Introduction, various possible HVDC configurations, unipolar and bipolar links, components of HVDC systems – converter, transformer, smoothing reactor, harmonic filter, Reactive power support.	06
6	HVDC Operation of 6-pulse controlled rectifier in inverting mode of operation, effect of source inductance, equivalent circuit representation of 6-pulse converter considering effect of source inductance, operation of 12-pulse converter.	06
7	Control of HVDC system Rectifier and inverter characteristics, mode stabilization, current control, voltage dependent current order limit, combined rectifier- inverter characteristics, wave blocking and by-passing, limitation of HVDC system using line commutated converters, modern HVDC systems HVDC light	06
	Term Work	
	rk shall comprise of	
1.	Tutorials based on each module in the syllabus content	

2. MCQ examination

Text Books	
1. Narain G. Hingorani, Laszlo Gyugyi, Understanding FACTS: Concepts and	
technology of flexible AC transmission systems, IEEE Press	
2. K. R. Padiyaar, HVDC Power transmission and system	
Reference Books	

1. K R Padiyaar, FACTS controllers in power transmission and distribution

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	1 to 7

Computer Aided Power System Analysis

Course Code	Course Name
PE-BTE708	Computer Aided Power System Analysis
<u>C</u>	DCA DCOC Neuroisel technismen announce deille

Course pre-requisites | PSA, PSOC, Numerical techniques, programming skills

Course Objectives

The objectives of this course are

1. To understand analysis of power systems using Computer methods.

2. To understand the advance techniques in the solution of power flow problem.

3. To understand the solution methods and techniques involved in power system analysis.

4. To understand the behavior of power system under healthy and faulty condition.

Course Outcomes

At the end of the course, students will demonstrate the ability to

- 1. Analyze the power system under symmetrical and unsymmetrical fault condition using Zbus
- 2. Appraise the use of matrix computation and optimization in the field of power system

3. Evaluate state of the complex power system by various state estimation tools.

4. Investigate the behavior of power system under different operating conditions

	Course Content	
Module No.	Details	Hrs.
1	Mathematical concepts: Sparse Matrices: Sparsity directed Optimal Ordering Schemes, Solution Algorithms – LU Factorization Numerical methods to solve non-linear equation: Gauss-Seidel, Newton Raphson method, Optimization Methods: Nonlinear constraint optimization, Lagrangian Multiplier approach, Linear programming, Least square Estimation	5
2	AC Power Flow Analysis: Preparing/using data files required for power flow studies such as line data, generation data, bus data. Ybus formation by Power flow solution algorithms such as Gauss Siedel, Newton Raphson, Fast Decoupled and DC power flow for multi- machine or IEEE systems. Power flow studies for distribution systems.	6
3	Analysis of Faulted Power System: Symmetrical and Asymmetrical Faults, Zbus Formulation, Short Circuit Analysis of Large Power Systems using Zbus.	5
4	Power System stability: Numerical solution of Swing equation using Forward Euler method, Runge-kutta 4 th order method, stability study of multi-machine system.	6
5	Load Forecasting Techniques: classification of forecasting, Introduction to time series, Linear regression, forecasting methodologies, estimation of average, trend & periodic components, time series approach, kalman filter approach, long	8

	term load forecasting for system planning. Introduction to Machine learning approach for load forecasting. Error analysis in load forecasting.	
6	Power System State Estimation : Introduction, Network Topology Processing, observability analysis, Linear and non- linear state estimation	6
7	Security Analysis: Basic Concepts, Static Security Analysis at Control Centre, Contingency Analysis, Contingency Selection.	6
	Term Work	
Term wor	k shall comprise of	
1	Tutorials based on each module in the syllabus content	

- 1. Tutorials based on each module in the syllabus content
- 2. MCQ examination

	Text Books
1.	Kothari. D.P, Nagrath I.J., "Modern Power System Analysis", TMH publication.
2.	Prabha Kundur, "Power System stability and Control", TMH Publication.
	Reference Books
1.	Grainger John J., Stevenson William D., "Power system Analysis", MC Graw
	Hill.
2.	Chakrabarti .A, Halder.S, "Power System Analysis-Operation and Control",
	PHI
3.	Hadi Sadat, "Power System Analysis", MC Graw Hill
4.	S. A. Soman, S. A. Khaparde, Shubha Pandit, "Computational Methods for
	Large Sparse Power System Analysis: An Object Oriented Approach",
	Springer
5.	M. A. Pai, D. Chatterjee, "Computer Techniques in Power System Analysis",
	McGraw Hill Education
6.	David S. Watkins, Fundamentals of Matrix Computations, 3rd Edition,
	Willey-Inter science, 2010

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	1 to 7

Electric Vehicle System Design

Course Code	Course Name
PE-BTE709	Electric Vehicle System Design
Course pre-requisites	Machines I and Machines II

Course Objectives

- 1. To illustrate the design philosophies used in the EV domain.
- 2. To explore the selection of power and control architecture of EV drives
- 3. To study the design aspects of EV battery packs and other auxiliary systems

Course Outcomes

Upon successful completion of the course, students should be able to

- 1. Select and size the electric motor for a particular EV application and performance criteria
- 2. Select and size the battery pack to meet desired EV performance and
- 3. Design the EV drive system with functional safety considerations.
- 4. Illustrate the use of hybrid energy source for EV performance improvement
- 5. Illustrate the design aspects of Automotive Subsystem

	Course Content		
Module No.	Details	Hrs.	
1	Selection/ Sizing of EV Electric Motors Electric Vehicle modelling, Tractive force calculations, Design considerations for 2W, 3W and 4W EVs; Torque, power and Speed requirement, Traction Limit, Maximum Acceleration Limit, Maximum Grade Limit, Vehicle Power Demand Vehicle Performance Envelope, and Vehicle Power Envelope; Vehicle Power Demand during Driving Cycles. Design considerations for EV motors and their cooling system. Application Examples of EV /HEV motors with vehicles and motor specifications.	08	
2	 Selection/ Sizing of Battery pack and other Energy Resource: Selection of type of Battery pack for 2W, 3W and 4W EVs, Battery pack sizing, Design considerations, Range per charge, range anxiety, EV motor power requirement, Impact of road conditions, environmental conditions and traffic conditions. High-Voltage Cabling and Disconnects, Safety in Battery Design, Testing for safety. Accelerated Reliability Testing of Electric Vehicles, Battery Cycle Life versus Peak Power and Rest Period. Selection and sizing of Fuel cell for FCEV, design considerations; Battery-ultra-capacitor hybrid combination sizing, performance analysis. Design considerations for Ultra-capacitor based EV, requirement of charging infra. 	06	

	Flywheel selection and sizing for EV/HEV applications.	
3	Automotive Subsystem Design:Electronic Control Unit (ECU) and its Control Features,Communications between ECUs, Control Software Development:Software-in-the-Loop (SIL) Simulation and Hardware-in-the-Loop(HIL) Simulation.Acceleration and braking control, regenerative braking;Automotive Steering Systems.Design considerations of HVAC controller	04
4	EV System integration: EMC design on ECU level, EMC design on system level and in special subsystems, Radiated emissions and Conducted emissions, EMI EMC measurements.	04
5	Design of Charging Infrastructure-1: Design considerations for AC charger: vehicle interface and charging protocol design. applicable charging standards. Installation guidelines and grid requirement for charger installations.	08
6	Design of Charging Infrastructure-2: Design of On-Board Charger (OBC)-Schematic, power topology and control, Power capacities, regenerative braking control. Design considerations of DC fast charger: vehicle interface and charging protocol design. Connectivity and applicable charging standards	06
7	Design with Functional Safety of Automotive Electronics:Functional Safety requirements of Automotive Electronics; ASILidentification and safety goal finalization, ISO 26262.Energy Storage integrity / protection: rupture and toxic gasmanagement; low energy stranding, Unintended vehicle movement,shock protection, and Elimination of potential thermal/ explosiveevent.Hazard and Risk Analysis (HARA) for different situations, Testingof vehicles for compliance of safety norms	06
	Term Work	
Term w	ork shall comprise of1. Tutorials, Case study based on IEEE papers or industrial visits2. MCQ examination	

Text Books / Reference Books

1. Design and Control of Automotive Propulsion Systems by Zongxuan Sun and Guoming Zhu, CRC Press, 2015

2. Electric Vehicle Machines and Drives Design, Analysis and Application by K. T. Chau, IEEE Press and Wiley, 2015

3. I. Hussein, Electric and Hybrid Vehicles: Design Fundamentals, CRC Press, 2003.

4. M. Ehsani, Y. Gao, S.E. Gay and Ali Emadi, Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design, CRC Press. 2005

5. Sheldon Williamsom, Energy Management Strategies for Electric and Plug-in Hybrid Vehicles, Springer 2013

6. J. Larminie and J. Lowry, Electric Vehicle Technology Explained, Wiley, 2003

7. EMC and Functional Safety of Automotive Electronics by Kai Borgeest, IET, 2018

Sr. No.	Examination	Module
1	T-I	1 and 2
2	T-II	3 and 4
3	End Sem	1 to 7

Computer Network

		Computer Petwork	
Course	e Code	Course Name	
OE-BTE701 Computer Network			
Course pre	e-requisites	Communication Engineering	
		Course Objectives	
The objecti	ves of this co		
•		ous types of networks	
2.	Introduce va	rious layers of computer network protocols	
		Course Outcomes	
Upon succe		tion of the course, students should be able to	
1.		process of communication in computer network	
2.	Simulate the	computer network.	
3.	Illustrate the	protocols of TCP/IP.	
		Course Content	
Module No.		Details	Hrs.
1	Types of control types	nce model and network architecture: communication (simplex, half duplex, full duplex), nnections, network topology types networks: peer to peer and client server networks, ardware- transmission technology-broadcast links and int links and scale–PAN, LAN, MAN, WAN, Interne software: protocol hierarchies, protocol, peers, network architecture, protocol stack, Connection d connectionless services, service primitives model: OSI,TCP/IP	06
2	Physical la Transmissi	yer: Guided Transmission Media ,Unguided on Media	03
3	Data link la Services pr layer, Fram CRC Error corre Flow contro		07
4	Medium A The Chann Protocols M CSMA/CD reservation	ccess Sub layer: el Allocation Problem, Multiple Access /ultiple access Aloha system, CSMA– ,CSMA/CA Controlled access – system, polling, token passing tion–FDMA,TDMA,CDMA Traditional Etheet- frame, addressing	07
5	Network la	ver:	08

	IPV4 addresses – address space, notations, classful, classless addressing Need for network layer, ipv4 datagram, fragmentation Routing table: Static, Dynamic, Routing protocol: Intra domain – Distance vector RIP, link state-OSPF, inter domain – path vector BGP.	
6	 Transport layer: Process to process delivery- client server paradigm, multiplexing, demultiplexing, connection less vs connection oriented service. UDP: user datagram, UDP operation: connectionless services, flow and error control, encapsulation and decapsulation, queuing. TCP: TCP services: process to process communication, stream delivery service, sending and receiving buffers, segments, full duplex communication. TCP features: sequence numbers and acknowledgement number, TCP segment, TCP connection, flow control, error control, congestion control. 	08
7	Application layer: Remote logging: TELNET, FTP	03

	Text Books	
1.	S. Tanenbaum, "Computer Networks", 4th Edition,	Prentice Hall, 2012.
Reference Books		
 B. F. Ferouzan, "Data and Computer Communication", 4 th Edition, Tata McGraw Hill, 2010. William Stallings, "Data and Computer Communication", 10thEdition, 2014 		
Sr. No.	Examination	Module

Sr. No.	Examination	Module
1	T-I	1, 2, Part of 3
2	T-II	Part of 3, 4, Part of 5
3	End Sem	1 to 7

Engineering Economics

		Engineering Economics	
Course	e Code	Course Name	
OE-B7	OE-BTE702 Engineering Economics		
Course pre	Course pre-requisites Basics of Project Management, statistics and mathematics, general knowledge about working of organizations		eneral
		Course Objectives	
The objective	ves of this co	purse are	
 2. Un provey eve 3. Lea bas 4. Un rese Upon succe 1. Approvey eve 2. Eva bas inv 3. Cal 	derstand som oblems of pre- en, benefit co- arn to evalua- sis of their ec- derstand the ources and it ssful comple ply appropria- blems of pre- en, benefit co- aluate the co- is of their ec- estment deci culate depre	te the cost effectiveness of engineering projects on the onomic viability. concepts of depreciation / appreciation of assets / as impact on their value. Course Outcomes tion of the course, students should be able to ate engineering economics methods for solving esent worth, annual cost, rate of return, payback, break ost ratio, etc. st effectiveness of engineering projects on the onomic viability and draw inferences for the	
	pact on prese	Course Content	
Module			Uma
No.		Details	Hrs.
1	 Concept of Efficiency Elements Opportun Break-Ev Elementary Basics, M 	cs: Flow in an economy, Law of Supply and Demand, of Engineering Economics: Definition, Scope, Types of y of Costs: Marginal Cost, Marginal Revenue, Sunk Cost,	03 03
2	 Introduct: Interest Payment Amount, 	rmulas and Their Applications ion, Time Value of Money Formulas: Single Payment Compound Amount, Single- Present Worth Amount, Equal-Payment Series Compound Equal-Payment Series Sinking Fund, Equal-Payment Series Worth Amount, Equal-Payment Series Capital Recovery	03

	Amount Uniform Credient Series Annual Equivalent Amount	
	Amount, Uniform Gradient Series Annual Equivalent Amount, Effective Interest Rate	
	 Bases for Comparison of Alternatives 	
	Present Worth Method of Comparison	06
	 Basics, Revenue-dominated Cash Flow Diagram, 	00
	 Dastes, Revenue-dominated Cash Flow Diagram, Cost-dominated Cash Flow Diagram 	
	• Cost-dominated Cash Flow Diagram	
	Future Worth Method	
	Basics, Revenue-dominated Cash Flow Diagram	
	 Cost-dominated Cash Flow Diagram 	
3	Cost-dominated Cash Flow Diagram	
5	Annual Equivalent Method	
	Basics, Revenue-dominated Cash Flow Diagram	
	 Cost-dominated Cash Flow Diagram 	
	 Alternate Approach 	
	• Alternate Approach	
	Rate of Return Method.	
	Advantages and disadvantages of each method.	
	Replacement and Maintenance Analysis	03
	 Basics, Types of Maintenance, Types of Replacement, 	05
	 Determination of Economic Life of an Asset 	
4	 Replacement of Existing Asset with a New Asset: Capital Recovery 	
-	with Return, Concept of Challenger and Defender	
	 Simple Probabilistic Model for Items Which Fail Completely. 	
	• Shiple i tobabilistic Model for items which i an completely.	
	Depreciation	03
	• Methods of Depreciation: Straight Line Method of Depreciation,	00
	Declining Balance Method of Depreciation, Sum-of-the-Years-	
5	Digits Method of Depreciation, Sinking Fund Method of	
	Depreciation, Service Output Method of Depreciation.	
		02
	Evaluation of Public Alternatives	
	Inventory Control	
	• Basics, Purchase Model with Instantaneous Replenishment and	
	without Shortages,	
6	 Manufacturing Model without Shortages 	04
	• Purchase Model with Shortages (Instantaneous Supply)	
	Manufacturing Model with Shortages	
	Make or Buy Decision	02
	Basics, Criteria for Make or Buy	
	• Approaches for Make or Buy Decision: Simple Cost Analysis,	
	Economic Analysis, Break-even Analysis	
7	Value Engineering	02
1	Basics, Functions, Aim,	
	• When to Apply Value Analysis, Value Analysis vs. Value	
	Engineering	
	Value Engineering Procedure, Advantages and Application Areas	0.1
		01
	Mathematical Models for Value Engineering	

	Text Books	
1. (Gerald J. Thuesen, W. J. Fabrycky, "Engineering Econo	omy", 8 th Edition, Prentice Hall
	nternational Series in Industrial and Systems Engineeri	
	R. Paneerselvam, "Engineering Economics", PHI Learn	e
3. I	eland Blank, Anthony Tarquin, "Basics of Engine	ering Economy, McGraw Hill
H	Higher Education Publications, 2008.	
	Reference Books	
1. 0	Chan S. Park, "Contemporary Engineering Economics",	5 th Edition, Pearson
F	Publication.	
2. I	2. Donald G. Newnan, Jerome P. Lavelle, Ted G. Eschenbach, "Engineering Economic	
A	Analysis", 12 th Edition, Oxford University Press.	
3. I	3. DeGarmo, E. Paul, Sallivan and Canada, "Engineering Economy", Collier MacMilan	
I	Ltd., USA.	
Sr. No.	Examination	Module

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	1 to 7

Embedded System

Course Code	Course Name
OE-BTE703	Embedded System
OE-BIE703	Elliocadea System

Course Objectives

Course pre-requisites

Computer architecture

The objectives of this course are

- 1. Introduction to embedded system design.
- 2. Study of ARM processor.
- 3. Study of embedded programming and hardware interfacing.
- 4. Understand the concept of RTOS.

Course Outcomes

Upon successful completion of the course, students should be able to

- 1. Define the unique characteristics of embedded systems.
- 2. Understand the basics of C and C++.
- 3. Discuss the interfacing challenges of embedded processors and peripherals.
- 4. Understand the concepts of Real Time Operating System

Course Content		
Module No.	Details	Hrs.
1	Introduction to Embedded systems: embedded system architecture, classifications of embedded systems, challenges and design issues in embedded systems (Design Metrics), Examples of embedded systems, fundamentals of embedded processor and microcontrollers, CISC vs. RISC, fundamentals of Von- neuman/Harvard architectures, types of	06
2	 microcontrollers, selection of Freelancer microcontrollers. Software Programming: C concepts and programming- data types, advanced data types- register, constants, IO operations, operators, operator precedence and associatively, Conditional statements & loops, arrays, single and double dimensional arrays, stings and string operations. Functions: Parameter passing-Pass by Value, Pass by Reference; creating modular programs using functions, Recursive functions. Structures & Unions: declaration, accessing members of structure, difference between structure and union, User Defined Data Types, Enumerated data type. Pointers: pointer basics and concepts, arrays and pointer relation, passing pointers to functions, dynamic memory allocation. Files and file operations. Linked lists, stacks and queues. Pre-processor directives, command line arguments. Basics of C++: features of C++, data types, standard I/O, arrays and strings in C++. Classes in C++. 	08
3	Introduction ARM Processor: ARM 7 instruction set, addressing modes, operating modes with ARM core, ARM7 TDMI modes,	08

1		1
	ADC, Timers, Interrupt structure. Byte ordering (LE, BE), Thumb	
	mode normal mode instructions changes, Pipeline utilization with	
	all register allocations, Floating to fixed point conversion	
	fundamentals. System design with ARM as key processor.DSP	
	features of ARM Core Digital Signal Controllers-DSC	
	differences with conventional micro controllers.	
	Hardware Interfacing: SCI, SPI, Timing generation and	06
	measurements. Analog interfacing and data acquisition, 7-Seg LED,	
4	LCD, Alphanumeric LCD, Graphic LCD displays, Communications	
4	and Networks - RS485 (2 and3 wire) and Modbus Protocol (Intro	
	only) - Ethernet and TCPIP Stack (Features	
	and Usage only) - CAN features and protocol.	
	Real-time concepts: real-time operating systems, Required RTOS	06
	services/capabilities (in contrast with traditional OS). Real-world	
	issues: blocking, unpredictability, interrupts, caching, Benefits of	
5	using RTOS - Concepts of Tasks/Threads/Process - Multitasking -	
	Task Scheduling - Task management - Inter-task communication	
	and Synchronization: - Device	
	Drivers - How to choose an RTOS.	
	Fundamentals of Design and Development: Program Modeling	04
6	tools	
	Testing and Debugging methodologies.	
	Applications of Embedded Systems: case studies	04
	- Industrial Automation	
7	- Medical	
	- Robotics	
	- Access Control Systems (Smart Cards, RFIDs, Finger Scan)	

Text Books

- 1. Rajkamal, Embedded Systems Architecture, Programming and Design, Tata McGraw Hill.
- 2. Shibu K V, Introduction to Embedded Systems, Tata Mc Graw Hil.
- 3. SriramIyer and Pankaj Gupta, Embedded Realtime Systems Programming, Tata McGraw Hil.

Reference Books

- 1. Jonathan W. Valvano ,Thomson, Embedded Microcomputer Systems.
- 2. David E. Simon, Pearson Education, An Embedded Software Primer.
- 3. Dr. K.V.K.Prasad, Dreamtech Press, Embedded real time system.

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	1 to 7

Internet of Things

	· · · ·		
Course Code		Course Name	
OE-BTE 704		Internet of Things	
Course pre-requisites Embedded System, Computer Programmin		g	
The objecti	ives of this co	Course Objectives	
1. S a	tudents will u pplications.	inderstand the concepts of Internet of Things and can able	
	Explored to the pace.	interconnection and integration of the physical world and t	he cyber
3. T	hey are also a	ble to design & develop IOT Devices.	
	0.1	Course Outcomes	
1	1	tion of the course, students should be able to	
		e concepts of Internet of Things.	
		protocols in wireless sensor network.	
	erformance.	plications in different domain and be able to analyze thei	Ľ
-		ic IoT applications on embedded platform.	
	inprement sus	Course Content	
Module			Hrs.
No.		Details	
	Introductio	on to IoT:	06
1	Defining I	oT, Characteristics of IoT, Physical design of IoT,	
1	Logical des	sign of IoT, Functional blocks of IoT, Communication	
	models & A	APIs.	
	IoT & M2	M:	06
2	Machine to	Machine, Difference between IoT and M2M,	
	Software de	efine Network.	
	Network &	& Communication aspects:	06
2		nedium access issues, MAC protocol survey,	
3	Survey rou	iting protocols, Sensor deployment & Node	
	discovery,	Data aggregation & dissemination.	
		Aanagement:	06
4		ing the Elements of IOT (Sensors, Connectivity through	
	network, A	pplication Layer), Overview of Sensors, Gateways,	
	Sensors Av	ailable in Market, Selecting the Right Sensor for the	
	Right Use c	case,	
	Considerati	ons for Mounting Sensors for Right Results.	
	Challenges	s in IoT:	06
5	Design cha	llenges, Development challenges, Security challenges,	
	Other chall	enges.	

	Domain specific applications of IoT:	06
6	Home automation, Industry applications, Surveillance	
	applications, Other IoT applications.	
	Developing IoTs:	06
	Introduction to Python, Introduction to different IoT tools,	
7	Developing applications through IoT tools, Developing sensor	
	based application through embedded system platform,	
	Implementing IoT concepts with python.	

Text Books

1. Dieter Uckelmann et.al, "Architecting the Internet of Things", Springer, 2011

Vijay Madisetti, Arshdeep Bahga, "Internet of Things: A Hands-On Approach".
 Waltenegus Dargie, Christian Poellabauer, "Fundamentals of Wireless Sensor

Networks: Theory and Practice"

Reference Books

1. Ian R. Sinclair, "Sensors and Transducer", Newnes, Third Edition.

2. Charalampos Doukas, "Building Internet of Things with the Arduino", Create space, April 2002

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	1 to 7

Project Stage I PR-BTE701

	1 ojeet stage 1 1 1 2 1 2 1 0 1
Course Code	Course Name
PR-BTE701	Project Stage-1
Course Pre-Requisites	Course pre-requisites: Recommended – all courses till semester VI

Course Objectives

Objectives of the course is:

- 1. Apply knowledge of principles of engineering for a developing society
- 2. To be able to do literature survey and be able to put it ethically towards solving an engineering problem
- 3. To develop an ability to empathize and formulate problem and analyze it

Course Outcomes

At the end of the course the student will be able to:

- 1. Identify the problem based on industrial, technical and/or socio economic need
- 2. Review of literature on the problem identified and Formulate objectives to achieve the desired solution.
- 3. Design methodology in conjunction with relevant codes, industry practices and contemporary research.
- 4. Apply principles of ethics and standards, skill of presentation and communication techniques.

Course Content		
Module No.	Description	Hrs.
1	Student shall study the topic of project work in terms of data collection, analysis, and inferencing. There would be two or more evaluation throughout the semester by committee of Faculty members	2+6(Self study)

Value Added Courses

1. Soft Computing I (VA-BTE01)

Course Objective: Provide knowledge of MATLAB/ SCILAB.

Course Outcome: Students will be able to develop good applications using MATLAB/ $\ensuremath{\mathsf{SCILAB}}$

Course content: Basic Introduction and Overview, Variables and Data types, Operation,. Control Structure, Function, Introduction to different tool boxes available, introduction to MATLAB simulink

2. Introduction to Python (VA-BTE02)

Course Objective: Provide knowledge of Python

Course Outcome: Students will be able to develop good applications using Python

Course content: Basic Introduction and Overview, Variables and Data types., Operations in Python, Control Structure, List, Tuples and Dictionary, Function, Introduction to turtle and some introduction to modules, Exception handling, Object oriented in python, Numpy, Matplotlib.



(Government Aided Autonomous Institute under Mumbai University) Andheri (W), Mumbai – 400058

COURSE CONTENTS

Sem. VIII

B.Tech. (ELECTRICAL) ENGINEERING

Academic Year: 2024-25

List of Courses

PC-BTE801: Electronic Design Laboratory
PE-BTE801: Power System Dynamics and Control
PE-BTE802: Smart Grid
PE-BTE803: HVDC Transmission Line
PE-BTE804: Power Quality and FACTS
PE-BTE805: Advanced Electric Drives
PE-BTE806: Industrial Automation
PE-BTE807: Industrial Electrical System
PE-BTE808: Advanced techniques in Power System Protection
PE-BTE809: Non-linear control system
OE-BTE801: Robotics
OE-BTE802: Power Plant Engineering
OE-BTE803: Electrical Engineering Materials
OE-BTE804: Medical Electronics
OE-BTE805: Image Processing
PR-BTE801: Project Stage II

Electronic Design Laboratory

Course Code		Course Name	
PC-BTE801		Electronic Design Laboratory	
Course pro	e-requisites	Electronic circuit, Analog Electronics,	
		Course Objectives	
The objecti	ves of this co		
		e fundamental principles of electronics system design.	
		he circuit design issues in the context of electronic system	n design.
	00	Course Outcomes	0
Upon succo	essful comple	tion of the course, students should be able to	
1	-	the practical issues related to practical	
		tion of applications using electronic circuits.	
2.	1	ropriate components, software and hardware platforms.	
		inted Circuit Board, get it made and populate/solder it wi	th
	components	S.	
4.	Work as a t	eam with other students to implement an application.	
		Course Content	
Module No.		Details	Hrs.
1	Sensors an	epts on measurements; Noise in electronic systems; d signal conditioning circuits;	4+4
2	based data	on to electronic instrumentation and PC acquisition;	4+4
3		system design, Analog system design, Interfacing of digital systems	4+4
4		systems, Electronic system design employing ollers, CPLDs, and FPGAs	4+4
5		n and layout;.	4+4
6		sembly considerations	4+4
7		jects involving electronic hardware (Analog, Digital, al) leading to implementation of an application	4+4

2. Lab assignments consist of design problems based on electronics/electrical system design.

3. Mini Project*

*Mini Project: There will be a course mini project where the students will be able to apply and integrate the knowledge gained during the course. The projects will be developed by teams of Four to Five students. The group has to present the project and submit the project report

Text Books

- 1. P. Horowitz and W. Hill, "The Art of Electronics", Cambridge University Press, 1997.
- 2. H.W.Ott, "Noise Reduction Techniques in Electronic Systems", Wiley, 1989.
- 3. W.C. Bosshart, "Printed Circuit Boards: Design and Technology", Tata McGraw Hill,1983

- 1. A. S. Sedra and K. C. Smith, "Microelectronic circuits", Oxford University Press, 2007.
- 2. G.L. Ginsberg, "Printed Circuit Design", McGraw Hill, 1991.

Sr. No.	Examination	Module
1	T-I	
2	T-II	
3	End Sem	1 to 7

Power System Dynamics and Control

Course Code Course Name		Course Name	
PE-B'	PE-BTE801 Power System Dynamics and Control		
Course pre-requisites Power System I and II			
•	•		
(F) 1	6.1.1	Course Objectives	
The objecti	ves of this co	urse are	
1.	To study the	e stability considerations in power system.	
2.	•	nd the different stability of power system and multi-mach	nine stability
	concept		
3.	•	voltage stability, PV, QV and PQ curves	
4.	To study of	improving the stability of power system	
TT		Course Outcomes	
Upon succe		tion of the course, students should be able to d appreciate the stability concept in the power network.	
1.		and relate the effects of various electrical parameter on st	abilit
2.	mplement	Course Content	aomt
Module			
No.		Details	Hrs.
		em stability considerations – definitions-classification	06
1		-rotor angle and voltage stability-synchronous	
	-	presentation –classical model load modeling concepts	
		of excitation systems-modeling of prime movers us machine: Higher order model representation	06
	•	haracteristics. Rotor position dependent model. D-Q	00
		ation. Model with Standard Parameters. Steady State	
2		f Synchronous Machine. Short Circuit T	
	•	us Machine-effect of field circuit dynamics-	
	-	citation system-small signal stability of Multi	
	Machine S		
		al stability – state space representation – Eigen values-	06
3		rices small signal stability of single machine	
	infinite bus	tability-swing equation-equal area criterion-solution	06
4	of swing	equation-Numerical m	VU
	0	tical clearing time and angle-effect of excitation system	
and governors			
5	Multi macl	nine stability –extended equal area criterion-transient	06
5		ction approach	
	-	bility – generation aspects - transmission system	06
6	-	bad aspects – PV curve – QV curve – PQ curve –	
	analysis wi		

	loads – load ability limit – sensitivity analysis-continuation power flow analysis - instability mechanisms examples.		
7	Methods of improving stability – transient stability enhancement – high speed fault clearing – steam turbine fast valving -high speed excitation systems- small signal stability enhancement power system stabilizers – voltage stability enhancement – reactive power control.	06	
Term Work			
Term work shall comprise of			
• Tutorials			

- Tutorials
- MCQ examination

Text Books	

- 1. Kundur, P., "Power System Stability and Control", McGraw-Hill International Editions.
- 2. Anderson, P.M. and Fouad, A.A., "Power System Control and Stability", John Wiley.

- 1. Van Cutsem, T. and Vournas, C., "Voltage Stability of Electric Power Systems", Springer
- 2. P.Sauer & M.A.Pai, Power System Dynamics & Stability, Prentice Hall, 1997

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	1 to 7

Smart Grid

Course Code	Course Name
PE-BTE802	Smart Grid
Course pre-requisites	

Course Objectives		
The objectives of this course are		
1. Discuss smart grid characteristics, opportunities and barriers		
2. Introduction to smart meters, smart substations		
3. Discuss micro grid, distributed energy resources, power quality		
management in smart grid.		
Course Outcomes		
Upon successful completion of the course, students should be able to		
1. Understand importance of smart grid		
2. Understand various components used in smart grid		
3. Understand the concepts of micro grid, distributed energy		
resources, power quality management in smart grid.		
4. Understand communication technology and security for smart gri	d	
Course Content		
Module Details	Hrs.	
No.	0(
Introduction to Smart Grid	06	
Evolution of Electric Grid, concept of Smart Grid, definition		
need of Smart Grid, functions of Smart Grid, opportunities an barriers of Smart Grid, difference between conventional an		
Smart Grid, concept of resilient and self healing Grid, preser		
development and international policies in Smart Grid, Cas		
studies of Smart Grid, CDM opportunities in Smart Grid.		
Smart Grid Technologies Part I	06	
Introduction to Smart Meters, real time prizing, Sma		
appliances Automatic Meter Reading (AMR) Outag		
² Annagement System (OMS), Plug in Hybrid Electric Vehicl		
(PHEV), Vehicle to Grid, Smart sensors, Home and building		
automation, Phase shifting transformers.	6	
Smart Grid Technologies Part II	06	
Smart substations, substation automation, feeder automation		
Geographic Information Systems (GIS), Intelligent Electronic		
3 Devices (IED) & their application in monitoring & protection		
Smart storage like Battery, SMES, Pumped Hydro Compresse		
Air Energy Storage, Wide Area Measurement System (WAMS		
Phase measurement unit (PMU).		

4	Micro grids and Distributed Energy Resources Concepts of micro grid, need and applications of micro grid, formation of micro grid, issues of interconnection, protection and control of micro grid, Plastic and organic solar cells, thin film solar cells, variable speed wind generators, fuel cells, micro turbines, captive power plants, integration of renewable energy sources.	06
5	Power Quality Management in Smart Grid Power quality & EMC in Smart Grid, power quality issues of grid connected renewable energy sources, power quality conditioners for Smart Grid, Web based Power Quality monitoring, Power quality Audit.	06
6	 Information & Communication Technology for Smart Grid Advanced Metering Infrastructure (AMI), Home Area Network (HAN), 6. Neighbourhood Area Network (NAN), Wide Area Network (WAN), Bluetooth, Zigbee, GPS, Wi-Fi, Wi-Max based communication, Wireless mesh network. 	06
7	Security for Smart Grid Basics of CLOUD computing and cyber security for Smart Grid, Broadband over Power Line (BPL), IP based protocols.	06
	Term Work	
Term wor	k shall comprise of	
	 Tutorials MCQ examination 	

Text Books

- 1. Ali Keyhani, Mohammad N. Marwali, Min Dai, Integration of Green and Renewable Energy in Electric Power Systems, Wiley.
- 2. Clark C. Gellings, The Smart Grid Enabling Energy Efficiency and Demand Response CRC press.
- Janaka Ekanayake, Nick Jenkins, KithsiriLiyanage, Jianzhong Wu, Akihiko Yokoyama, Smart Grid – Technology and Applications, Wiley.
- 4. Jean Claude Sabonnadière, NouredineHadjsaid, Smart Grids, Wiley Blackwell.
- Peter S. Fox, Penner, Smart Power Climate Changes, the Smart Grid and the Future of Electric Utilities, Island Press, 1st Edition 8th June 2010.
- 6. Stuart Borlase, Smart Grids (Power Engineering) CRC Press.
- 7. S.Chowdhury, S. P. Chowdhury, P. Crossley, Microgrids and Active Distribution Networks, Institution of Engineering and Technology, 30th June 2009.

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	1 to 7

HVDC Transmission System

Course Code	Course Name
PE-BTE803	HVDC Transmission System

Course pre-requisites

	Course Objectives		
5	ves of this course are		
	1. Understand the advantages of dc transmission over ac transmission.		
2.	Understand the operation of Line Commutated Converters		
	and Voltage Source Converters.		
3.	Understand the control strategies used in HVdc transmission system.		
4.	Understand the improvement of power system stability using an HV	dc system	
	Course Outcomes		
Upon succe	essful completion of the course, students should be able to		
1.	Understand the advantages of dc transmission over ac transmission.		
2.	Understand the operation of Line Commutated Converters		
	and Voltage Source Converters.		
3.	Understand the control strategies used in HVDC transmission system	1.	
4.	Understand the improvement of power system stability using an HV.	DC system.	
	Course Content		
Module	Details	Hrs.	
No.			
	Transmission Technology	05	
	Comparison of AC and dc Transmission (Economics, Technical		
	Performance and Reliability). Application of DC Transmission.		
1	Types of		
	HVDC Systems. Components of a HVdc system. Line		
	Commutated Converter and Voltage Source Converter based		
	systems.		
	Analysis of Line Commutated and Voltage Source Converters	10	
	Line Commutated Converters (LCCs): Six pulse converter,		
	Analysis neglecting commutation overlap, harmonics, Twelve		
	Pulse Converters. Inverter Operation. Effect of Commutation		
	Overlap. Expressions for average dc voltage, AC current and		
2	reactive power absorbed by the converters. Effect of		
	Commutation Failure, Misfire and Current Extinction in LCC		
	links.		
	Voltage Source Converters (VSCs): Two and Three-level VSCs.		
	PWM schemes: Selective Harmonic Elimination, Sinusoidal		
	Pulse Width Modulation. Analysis of a six pulse converter.		

	Equations in the rotating frame. Real and Reactive power control	
	using a VSC.	
3	Control of HVdc Converters: Principles of Link Control in a LCCHVdc system. Control Hierarchy, Firing Angle Controls– Phase-Locked Loop, Current and Extinction Angle Control, Starting and Stopping of a Link. Higher level Controllers Power control, Frequency Control, Stability Controllers. Reactive Power Control. Principles of Link Control in a VSC HVdc system: Power flow and dc Voltage Control. Reactive Power Control/AC voltage regulation	10
4	Components of HVdc systems: Smoothing Reactors, Reactive Power Sources and Filters in LCC HVdc systems DC line: Corona Effects. Insulators, Transient Over-voltages. dc line faults in LCC systems. dc line faults in VSC systems. dc breakers. Monopolar Operation. Ground Electrodes	08
5	Stability Enhancement using HVdc Control Basic Concepts: Power System Angular, Voltage and Frequency Stability. Power Modulation: basic principles – synchronous and asynchronous links. Voltage Stability Problem in AC/dc systems	05
6	MTdc Links Multi-Terminal and Multi-Infeed Systems. Series and Parallel MTdc systems using LCCs. MTdc systems using VSCs. Modern Trends in HVdcTechnology. Introduction to Modular Multi-level Converters.	04
	Term Work	
Term wor	k shall comprise of	
	1. Tutorials	
	2. MCQ examination	

Text Books

- K R Padiyar, "HVDC Power Transmission Systems", New Age International Publishers, 2011.
 F W Kirzbark, "Direct Correct Transmission," Vol 1, Wiley, International, 1071
- 2. E W Kimbark, "Direct Current Transmission", Vol.1, Wiley-Interscience, 1971. Reference Books
 - 1. J Arillaga, "High Voltage Direct Current Transmission", Peter Peregrinus Ltd., 1983

Sr. No.	Examination	Module
1	T-I	1, Part of 2
2	T-II	Part of 2, Part of 3
3	End Sem	1 to 6

Power Quality and FACTS

Course Code Course Name			
PE-BTE804 Power Quality and FACTS			
Course pro	e-requisites		
		Course Objectives	
The objecti	ves of this co	Course Objectives	
		the characteristics of ac transmission and the	
	effect of she	unt and series reactive compensation.	
2.		the working principles of FACTS	
2		their operating characteristics.	
		the basic concepts of power quality. the working principles of devices to improve power qual	itx
+.	Onderstand	Course Outcomes	ity.
Upon succe	essful comple	etion of the course, students should be able to	
-	-	the characteristics of ac transmission and the	
		unt and series reactive compensation.	
2.		the working principles of FACTS	
2		their operating characteristics.	
 Understand the basic concepts of power quality. Understand the working principles of devices to improve power quality. 			
4.	Understand	Course Content	ity.
Module			
No.		Details	Hrs.
	Tuesday	on Lines and Series/Shunt Reactive Power	04
			V4
	Compensa	tion Basics of AC Transmission. Analysis of	04
1	Compensa uncompena	tion Basics of AC Transmission. Analysis of sated AC transmission lines.	04
1	Compensa uncompen PassiveRea	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series	04
1	Compensa uncompens PassiveRes compensat	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of	04
1	Compensa uncompensa PassiveRea compensat Series and	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of Shunt Compensation.	
1	Compensa uncompensa PassiveRea compensat Series and Thyristor-I	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of Shunt Compensation. based Flexible AC Transmission Controllers	04
1	Compensa uncompensa PassiveRes compensat Series and Thyristor-t (FACTS) I	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of Shunt Compensation.	
1	Compensa uncompensa PassiveRes compensat Series and Thyristor-I (FACTS) I FACTS de Controlled	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of <u>Shunt Compensation</u> . based Flexible AC Transmission Controllers Description and Characteristics of Thyristor-based wices: Static VAR Compensator (SVC), Thyristor Series Capacitor (TCSC), Thyristor Controlled	
	Compensa uncompensa PassiveRes compensat Series and Thyristor-t (FACTS) I FACTS de Controlled Braking Re	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of <u>Shunt Compensation.</u> based Flexible AC Transmission Controllers Description and Characteristics of Thyristor-based wices: Static VAR Compensator (SVC), Thyristor Series Capacitor (TCSC), Thyristor Controlled esistor and Single Pole Single Throw (SPST) Switch.	
	Compensa uncompensa PassiveRea compensat Series and Thyristor-I (FACTS) I FACTS de Controlled Braking Re Configurat	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of Shunt Compensation. Description and Characteristics of Thyristor-based vices: Static VAR Compensator (SVC), Thyristor Series Capacitor (TCSC), Thyristor Controlled esistor and Single Pole Single Throw (SPST) Switch. ions/Modes of Operation, Harmonics and control of	
	Compensa uncompensa PassiveRea compensat Series and Thyristor-I (FACTS) I FACTS de Controlled Braking Re Configurat SVC and T	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of <u>Shunt Compensation.</u> based Flexible AC Transmission Controllers Description and Characteristics of Thyristor-based vices: Static VAR Compensator (SVC), Thyristor Series Capacitor (TCSC), Thyristor Controlled esistor and Single Pole Single Throw (SPST) Switch. ions/Modes of Operation, Harmonics and control of CCSC. Fault Current Limiter.	06
	Compensa uncompensa PassiveRea compensat Series and Thyristor-t (FACTS) I FACTS de Controlled Braking Re Configurat SVC and T Voltage So	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of <u>Shunt Compensation.</u> based Flexible AC Transmission Controllers Description and Characteristics of Thyristor-based vices: Static VAR Compensator (SVC), Thyristor Series Capacitor (TCSC), Thyristor Controlled esistor and Single Pole Single Throw (SPST) Switch. ions/Modes of Operation, Harmonics and control of <u>CCSC. Fault Current Limiter.</u> burce Converter based (FACTS) controllers	
	Compensa uncompensa PassiveRea compensat Series and Thyristor-I (FACTS) I FACTS de Controlled Braking Re Configurat SVC and T Voltage Se	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of Shunt Compensation. Dased Flexible AC Transmission Controllers Description and Characteristics of Thyristor-based vices: Static VAR Compensator (SVC), Thyristor Series Capacitor (TCSC), Thyristor Controlled esistor and Single Pole Single Throw (SPST) Switch. ions/Modes of Operation, Harmonics and control of CCSC. Fault Current Limiter. Durce Converter based (FACTS) controllers Durce Converters (VSC): Six Pulse VSC, Multi-pulse	06
	Compensa uncompensa PassiveRea compensat Series and Thyristor-I (FACTS) I FACTS de Controlled Braking Re Configurat SVC and T Voltage Se and Multi-	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of <u>Shunt Compensation</u> . based Flexible AC Transmission Controllers Description and Characteristics of Thyristor-based wices: Static VAR Compensator (SVC), Thyristor Series Capacitor (TCSC), Thyristor Controlled esistor and Single Pole Single Throw (SPST) Switch. ions/Modes of Operation, Harmonics and control of <u>CCSC. Fault Current Limiter</u> . burce Converter based (FACTS) controllers burce Converters (VSC): Six Pulse VSC, Multi-pulse elevel Converters, Pulse-Width Modulation for VSCs.	06
	Compensa uncompensa PassiveRea compensat Series and Thyristor-I (FACTS) I FACTS de Controlled Braking Re Configurat SVC and T Voltage Se and Multi- Selective	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of <u>Shunt Compensation.</u> based Flexible AC Transmission Controllers Description and Characteristics of Thyristor-based wices: Static VAR Compensator (SVC), Thyristor Series Capacitor (TCSC), Thyristor Controlled esistor and Single Pole Single Throw (SPST) Switch. ions/Modes of Operation, Harmonics and control of <u>CSC. Fault Current Limiter.</u> burce Converter based (FACTS) controllers burce Converters (VSC): Six Pulse VSC, Multi-pulse elevel Converters, Pulse-Width Modulation for VSCs. Harmonic Elimination, Sinusoidal PWM andSpace	06
2	Compensa uncompensa PassiveRea compensat Series and Thyristor-I (FACTS) I FACTS de Controlled Braking Re Configurat SVC and T Voltage Se and Multi- Selective Vector M	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of <u>Shunt Compensation.</u> based Flexible AC Transmission Controllers Description and Characteristics of Thyristor-based wices: Static VAR Compensator (SVC), Thyristor Series Capacitor (TCSC), Thyristor Controlled esistor and Single Pole Single Throw (SPST) Switch. ions/Modes of Operation, Harmonics and control of <u>CSC. Fault Current Limiter.</u> burce Converter based (FACTS) controllers burce Converters (VSC): Six Pulse VSC, Multi-pulse elevel Converters, Pulse-Width Modulation for VSCs. Harmonic Elimination, Sinusoidal PWM andSpace	06
2	Compensa uncompensa PassiveRea compensat Series and Thyristor-I (FACTS) I FACTS de Controlled Braking Re Configurat SVC and T Voltage So and Multi- Selective Vector M Reactive F	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of <u>Shunt Compensation</u> . Description and Characteristics of Thyristor-based vices: Static VAR Compensator (SVC), Thyristor Series Capacitor (TCSC), Thyristor Controlled esistor and Single Pole Single Throw (SPST) Switch. ions/Modes of Operation, Harmonics and control of <u>CCSC. Fault Current Limiter</u> . Durce Converter based (FACTS) controllers Durce Converters, Pulse-Width Modulation for VSCs. Harmonic Elimination, Sinusoidal PWM andSpace Modulation. STATCOM: Principle of Operation,	06
2	Compensa uncompensa PassiveRea compensat Series and Thyristor-I (FACTS) I FACTS de Controlled Braking Re Configurat SVC and T Voltage Se and Multi- Selective Vector M Reactive F Synchrono Flow Cont	tion Basics of AC Transmission. Analysis of sated AC transmission lines. active Power Compensation. Shunt and series ion at the mid-point of an AC line. Comparison of <u>Shunt Compensation</u> . based Flexible AC Transmission Controllers Description and Characteristics of Thyristor-based wices: Static VAR Compensator (SVC), Thyristor Series Capacitor (TCSC), Thyristor Controlled esistor and Single Pole Single Throw (SPST) Switch. ions/Modes of Operation, Harmonics and control of <u>CSC. Fault Current Limiter</u> . burce Converter based (FACTS) controllers burce Converters, Pulse-Width Modulation for VSCs. Harmonic Elimination, Sinusoidal PWM andSpace fodulation. STATCOM: Principle of Operation, Power Control: Type I and Type II controllers, Static	06

	Other Devices: GTO Controlled Series Compensator. Fault	
	Current Limiter.	
4	4 Application of FACTS Application of FACTS devices for power-flow control and stability improvement. Simulation example of power swing damping in a single- machine infinite bus system using a TCSC. Simulation example of voltage regulation of transmission mid- point voltage using a STATCOM	
5	Power Quality Problems in Distribution Systems Power Quality problems in distribution systems: Transient and Steady state variations in voltage and frequency. Unbalance, Sags, Swells, Interruptions, Wave-form Distortions: harmonics, noise, notching, dc- offsets, fluctuations. Flicker and its measurement. Tolerance of Equipment: CBEMA curve.	04
6	DSTATCOM Reactive Power Compensation, Harmonics and Unbalance mitigation in Distribution Systems using DSTATCOM and Shunt Active Filters. Synchronous Reference Frame Extraction of Reference Currents. Current Control Techniques in for DSTATCOM	08
7	Dynamic Voltage Restorer and Unified Power QualityConditioner Voltage Sag/Swell mitigation: Dynamic VoltageRestorer – Working Principle and Control Strategies. SeriesActive Filtering. Unified PowerQuality Conditioner (UPQC): Working Principle.Capabilities and Control Strategies.	06
	Term Work	1
Term wo	rk shall comprise of	
1.	. Tutorials	
2	MCO examination	

2. MCQ examination

Text Books

1. J. Arrillaga, M. R. Watson, S. Chan, Power System Quality Assessment, John Wiley and Sons.

- 1. M. H. J. Bollen, Understanding Power Quality Problems, Voltage Sag and Interruptions, New York IEEE press, 2000 Series on Power Engineering.
- 2. R. C. Dugan, Mark F. McGranghan, Surya Santoso, H. Wayne Beaty, Electrical Power System Quality, McGraw Hill Publication:
- 3. EnriquesAcha, Manuel Madrigal, Power System Harmonics Computer Modeling and Analysis, John Wiley and Sons Ltd.
- 4. Ewald F. Fuchs, Mohammad A. S. Masoum, Power Quality in Power Systems and Electrical Machines.
- 5. G. J. Heydt, Electric Power Quality, Stars in Circule publications.
- 6. IEEE Std. 519-1992, IEEE recommended practices and requirements for harmonics control in electrical power system

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	1 to 7

Advanced Electric Drives

Cours	e Code	Course Name	
PE-BTE805		Advanced Electric Drives	
Course pre-requisites Electric Drives			
The objecti	ves of this co	Course Objectives	
5		operation of power electronic converters and their contro	l strategies.
2.	Introduce ve	ector control strategies for ac motor drives	-
3.	Discuss the	implementation of the control strategies using digital sign	nal processors
Upon succe	esful comple	tion of the course, students should be able to	
		the operation of power electronic converters and their con	ntrol
	strategies.		
		the vector control strategies for ac motor drives	
3.		the implementation of the control	
	strategies us	sing digital signal processors. Course Content	
Module			
No.		Details	Hrs.
		nverters for AC drives	05
1		rol of inverter, selected harmonic elimination, space lulation, current control of VSI, three level inverter,	
		opologies, SVM for 3 level inverter	
		nverters for DC drives	05
		fier with boost chopper, PWM converter as line side	
2	rectifier,	inverters with self-commutated devices. Control	
		bridge as a 4-Q drive.	
		motor drives	08
		ransformations and reference frame theory, modeling of	
3		nachines, voltage fed inverter control-v/f	
	control, veo	ctor control, direct torque and flux	
		ous motor drives	06
4		of synchronous machines, open loop v/f control,	
-		trol, direct torque control, CSI fed synchronous motor	
	drives.	t magnet motor drives	06
		on to various PM motors, BLDC and PMSM drive	VU
5		on, comparison, block diagrams, Speed and torque	
	control in		
	BLDC and		06
6		reluctance motor drives of switched reluctance motors, various topologies	06
0		rives, comparison, Closed loop speed and torque	

	control of SRM	
	DSP based motion control	06
7	Use of DSPs in motion control, various DSPs available,	
/	realization of some basic blocks in DSP for implementation of	
	DSP based motion control.	
	Term Work	
Term wo	rk shall comprise of	
	1. Tutorials	
	2. MCQ examination	

Text Books

1. K. Bose, "Modern Power Electronics and AC Drives", Pearson Education, Asia, 2003.

- 1. P. C. Krause, O. Wasynczuk and S. D. Sudhoff, "Analysis of Electric Machineryand Drive Systems", John Wiley & Sons, 2013.
- 2. H. A. Taliyat and S. G. Campbell, "DSP based Electromechanical Motion Control", CRC press, 2003.
- 3. R. Krishnan, "Permanent Magnet Synchronous and Brushless DC motor Drives", CRC Press, 2009

Sr. No.	Examination	Module
1	T-I	1, 2, Part of 3
2	T-II	Part of 3, 4
3	End Sem	1 to 7

Industrial Automation

Course Code	Course Name		
PE-BTE806	Industrial Automation		
Course pre-requisites			
	Course Objectives		
The objectives of this as	<u> </u>		
The objectives of this co			
1. Understa	1. Understand architecture of Industrial Automation system.		
2. Overview	2. Overview of industrial control system.		
3. Overview of elements of automation system.			
4. Understand performance objectives of process automation.			
Course Outcomes			
Upon successful completion of the course, students should be able to			
1. Understand Architecture of Industrial Automation Systems.			
2. Understa	2. Understand the process of tuning and draw P & I diagrams.		
3. Understa	nd elements of industrial automation.		
4. Get knowledge of design methodology for industrial automation systems			
	Course Content		

Course Content		
Module No.	Details	Hrs.
1	Introduction Industrial Automation and Control and Architecture of Industrial Automation Systems	05
2	Industrial Control System: P, I, D & Tuning with reference to Process Control & Drives Control	05
3	Process representation: P & I Diagrams and Interpretation, block diagrams	08
4	Design methodology User Requirement Specifications (URS) System (Or Software) Requirement Specifications (SRS) Factory & Site Acceptance Tests (FAT & SAT) Quality Assurance System	06
5	 Elements Industrial Automation (a) Five tier concept (Sensors to Boardroom) Field Devices (Instruments, IEDs, Lab Equipment etc, Smart & Conventional) Controllers (PLC, DCS, RTU, DDCs) SCADA/HMI & Database Elements Industrial Automation (b) Higher level applications (MIS/MES/Optimization / ERP etc) IT Infrastructure (Servers, Work Stations, Engineering Stations, Gateways, FEP, Communication Networks etc) Protocols: 7 layer model, TCP/IP Ethernet, Modbus TCP/IP & RTU, - Profibus, IEC61850, BACNet, OPC etc 	06
6	Performance objectives: Response times (At various levels)	06

	Availability Calculation for the System (MTBF &	
	MTTR) Resolution, Linearity, Accuracy	
	Case Study(Any one)	06
	-Electric Drives : Introduction, Energy Saving with	
7	Adjustable Speed Drives	
	- Introduction to Production Control Systems	
	- Introduction to CNC Machines	
	Term Work	
Term wo	ork shall comprise of	
	1. Tutorials	
	2. PLC programs/ mini project	
	3. MCQ examination	
	*Mini project: There will be a course project where the studen	ts will be able to

*Mini project: There will be a course project where the students will be able to apply and integrate the knowledge gained during the course. The projects will be developed by teams of Two to Four students and will consist of design of any one Automation application

Text Books

- 1. Industrial Instrumentation, Control and Automation, S. Mukhopadhyay, S. Sen and A. K. Deb, Jaico Publishing House, 2013
- 2. Programmable controllers: Principle and Applications, Webb J.W, PHI New Delhi
- 3. Industrial Electronics, Thomos E. Kissell, PHI.

- 1. Chemical Process Control, An Introduction to Theory and Practice, George Stephanopoulos, Prentice Hall India, 2012.
- 2. Process Control Instrumentation, Curtis . D. Jhonson, Pearson (8th edition)
- 3. Electric Motor Drives, Modelling, Analysis and Control, R. Krishnan, Prentice Hall India, 2002
- 4. Hydraulic Control Systems, Herbert E. Merritt, Wiley, 1991
- 5. PID Controllers: Theory, Design, and Tuning, Karl Astrom and Tore Hagglund
- 6. Industrial Instrumentation and Control By. S.K. Singh The McGraw Hill Companies.
- 7. Industrial Electronics and Control, S K Bhattacharya, S Chatterjee, Ttti Chandigarh.

Sr. No.	Examination	Module
1	T-I	1,2, Part of 3
2	T-II	Part of 3, 4
3	End Sem	1 to 7

Industrial Electrical Systems

		•		
Course Code		Course Name		
PE-BTE807 Industrial Electrical Systems				
Course pre-requisites				
The objecti	ves of this co	Course Objectives		
•		the electrical wiring systems for residential,		
		and industrial consumers, representing the		
2		h standard symbols and drawings, SLD.		
2. 3.		various components of industrial electrical systems. I select the proper size of various electrical system compo	onents	
5.	Anaryze and	Course Outcomes	Shents.	
Upon succe	essful comple	tion of the course, students should be able to		
-	Understand	the electrical wiring systems for residential,		
		and industrial consumers, representing the		
	•	h standard symbols and drawings, SLD.		
		various components of industrial electrical systems.		
3.	Analyze and	l select the proper size of various electrical system compo Course Content	onents.	
Module				
No.		Details	Hrs.	
	Electrical C		00	
		System Components	08	
	LT system	n wiring components, selection of cables, wires,	08	
	LT system switches,	n wiring components, selection of cables, wires, distribution box, metering system, Tariff structure,	08	
1	LT system switches,	n wiring components, selection of cables, wires,	08	
1	LT system switches, o protection current characterist	n wiring components, selection of cables, wires, distribution box, metering system, Tariff structure, components- Fuse, MCB, MCCB, ELCB, inverse tics, symbols, single line diagram (SLD) of a wiring	08	
1	LT system switches, o protection current characterist system, Co	n wiring components, selection of cables, wires, distribution box, metering system, Tariff structure, components- Fuse, MCB, MCCB, ELCB, inverse tics, symbols, single line diagram (SLD) of a wiring ontactor, Isolator, Relays, MPCB, Electric shock and	08	
1	LT system switches, of protection current characterist system, Co Electrical s	n wiring components, selection of cables, wires, distribution box, metering system, Tariff structure, components- Fuse, MCB, MCCB, ELCB, inverse tics, symbols, single line diagram (SLD) of a wiring ontactor, Isolator, Relays, MPCB, Electric shock and safety practices		
1	LT system switches, o protection current characterist system, Co Electrical s Residential	n wiring components, selection of cables, wires, distribution box, metering system, Tariff structure, components- Fuse, MCB, MCCB, ELCB, inverse tics, symbols, single line diagram (SLD) of a wiring ontactor, Isolator, Relays, MPCB, Electric shock and	08	
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	LT system switches, o protection current characterist system, Co Electrical s Residential Types of p rules and g of wire, rat	n wiring components, selection of cables, wires, distribution box, metering system, Tariff structure, components- Fuse, MCB, MCCB, ELCB, inverse tics, symbols, single line diagram (SLD) of a wiring ontactor, Isolator, Relays, MPCB, Electric shock and safety practices I and Commercial Electrical Systems residential and commercial wiring systems, general guidelines for installation, load calculation and sizing ting of main switch, distribution board and protection		
2	LT system switches, o protection current characterist system, Co Electrical s Residential Types of p rules and g of wire, rat devices,	n wiring components, selection of cables, wires, distribution box, metering system, Tariff structure, components- Fuse, MCB, MCCB, ELCB, inverse tics, symbols, single line diagram (SLD) of a wiring ontactor, Isolator, Relays, MPCB, Electric shock and safety practices I and Commercial Electrical Systems residential and commercial wiring systems, general guidelines for installation, load calculation and sizing ting of main switch, distribution board and protection earthing system calculations, requirements of		
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	LT system switches, o protection current characterist system, Co Electrical s Residential Types of t rules and g of wire, rat devices, commercia lamps, eart selection an Illuminatio	n wiring components, selection of cables, wires, distribution box, metering system, Tariff structure, components- Fuse, MCB, MCCB, ELCB, inverse tics, symbols, single line diagram (SLD) of a wiring ontactor, Isolator, Relays, MPCB, Electric shock and <u>safety practices</u> I and Commercial Electrical Systems residential and commercial wiring systems, general guidelines for installation, load calculation and sizing ting of main switch, distribution board and protection earthing system calculations, requirements of l installation, deciding lighting scheme and number of hing of commercial installation, <u>nd sizing of components</u> on Systems		
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2	LT system switches, o protection current characterist system, Co Electrical s Residential Types of p rules and g of wire, rat devices, commercia lamps, eart selection at Illuminatio Understanc candle por	n wiring components, selection of cables, wires, distribution box, metering system, Tariff structure, components- Fuse, MCB, MCCB, ELCB, inverse tics, symbols, single line diagram (SLD) of a wiring ontactor, Isolator, Relays, MPCB, Electric shock and safety practices I and Commercial Electrical Systems residential and commercial wiring systems, general guidelines for installation, load calculation and sizing ting of main switch, distribution board and protection earthing system calculations, requirements of l installation, deciding lighting scheme and number of hing of commercial installation, nd sizing of components on Systems ling various terms regarding light, lumen, intensity, wer, lamp efficiency, specific consumption, glare,	08	
	LT system switches, o protection current characterist system, Co Electrical s Residential Types of t rules and g of wire, rat devices, commercia lamps, eart selection at Illuminatio Understanc candle poy space to h	n wiring components, selection of cables, wires, distribution box, metering system, Tariff structure, components- Fuse, MCB, MCCB, ELCB, inverse tics, symbols, single line diagram (SLD) of a wiring ontactor, Isolator, Relays, MPCB, Electric shock and safety practices I and Commercial Electrical Systems residential and commercial wiring systems, general guidelines for installation, load calculation and sizing ting of main switch, distribution board and protection earthing system calculations, requirements of l installation, deciding lighting scheme and number of hing of commercial installation, nd sizing of components on Systems ling various terms regarding light, lumen, intensity,	08	
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2	LT system switches, o protection current characterist system, Co Electrical s Residential Types of t rules and g of wire, rat devices, commercia lamps, eart selection at Illuminatio Understand candle pov space to h various illu luminaries illuminatio	n wiring components, selection of cables, wires, distribution box, metering system, Tariff structure, components- Fuse, MCB, MCCB, ELCB, inverse tics, symbols, single line diagram (SLD) of a wiring ontactor, Isolator, Relays, MPCB, Electric shock and safety practices I and Commercial Electrical Systems residential and commercial wiring systems, general guidelines for installation, load calculation and sizing ting of main switch, distribution board and protection earthing system calculations, requirements of l installation, deciding lighting scheme and number of hing of commercial installation, nd sizing of components on Systems ding various terms regarding light, lumen, intensity, wer, lamp efficiency, specific consumption, glare, neight ratio, waste light factor, depreciation factor, umination schemes, Incandescent lamps and modern	08	

	premises, flood lighting.	
	Industrial Electrical Systems I	08
	HT connection, industrial substation, Transformer selection,	
	Industrial loads, motors, starting of motors, SLD, Cable and Switchgear selection, Lightning Protection, Earthing design,	
4	Power factor correction – kVAR calculations, type of	
	compensation, Introduction to PCC, MCC panels.	
	Specifications of LT Breakers, MCB and other LT panel	
	components.	
	Industrial Electrical Systems II (6 Hours)	06
5	DG Systems, UPS System, Electrical Systems for the elevators,	
U	Battery banks, Sizing the DG, UPS and Battery Banks, Selection	
	of UPS and Battery Banks.	
	Industrial Electrical System Automation	06
	Study of basic PLC, Role of in automation, advantages of	
6	process automation, PLC based control system design, Panel	
	Metering and Introduction to SCADA system for distribution	
	automation.	
	Term Work	
Term wo	rk shall comprise of	
	2. Tutorials	
	2 MCO examination	

3. MCQ examination

Text Books 1. S. L. Uppal and G. C. Garg, "Electrical Wiring, Estimating & Costing", Khanna publishers, 2008. 2. K. B. Raina, "Electrical Design, Estimating & Costing", New age International, 2007. Reference Books 3. S. Singh and R. D. Singh, "Electrical estimating and costing", Dhanpat Rai and Co., 1997. 4. Web site for IS Standards. 5. H. Joshi, "Residential Commercial and Industrial Systems", McGraw Hill Education, 2008.

Sr. No.	Examination Module	
1	T-I	1, Part of 2
2	T-II	Part of 2, 3, Part of
		4
3	End Sem	1 to 6

Advanced techniques in Power System Protection

Cours	e Code	Course Name	
OE-BTE808		Advanced techniques in Power System Protection	
Course pre-requisites Switchgear and Protection			
		Course Objections	
The objecti	ives of this co	Course Objectives	
		art and science of numerical relay technology.	
		e hardware description of relaying system.	
		Course Outcomes	
Upon succe	essful comple	tion of the course, students should be able to	
		ern protection practices.	
2. A	appreciate new	trends in relay technologies	
	Γ	Course Content	ſ
Module No.		Details	Hrs.
	Review of	Relaying Practices: Evolution of digital relays from	5
1		hanical relays, Review of protection philosophies for	
1	transmissio	on lines, generators and transformers. Modeling of	
	Current and	d voltage transformers	
	Mathema	ntical background to protection algorithms: Finite	8
	difference	e Techniques, Interpolation formulae: Forward,	
2	backwar	d and central difference interpolation, Numerical	
	different	iation, Curve fitting and smoothing, Least squares	
		Fourier series and Fourier transform	
	Numerical	Relay: architecture, sampling theorem, anti-	5
3		ter, Fourier Algorithm, Full cycle window	
	-	for phasor estimation	
	Transmiss	ion Line Protection:	8
4		elay scheme for three phase line, Different relay	
·	-	for distance protection, Out of step blocking and	
	tripping sc		
~	-	ferential Protection: protection of generator,	8
5	protection	r, bus bar protection, Travelling wave based	
	1	Relaying: Need for adaptive relaying, Adaptive	4
6	-	r transmission lines, transformer, Auto-reclosing.	
7		a Measurement Applications:	4
		chitecture, WAMS based out of step relaying,	
		n of back up zones, Intelligent load shedding,	
	Intelligent		
		Term Work	
	k shall comp	rise of	
	Tutorials		
2	. MCQ exam	ination	

	Text Books		
1.	A.G. Phadke and J. S. Thorp, "Computer Relaying for Power Systems",		
	Wiley/Research studies Press, 2009		
2.	A.T. Johns and S. K. Salman, "Digital Protection of Power Systems", IEEE Press, 1999		
	Reference Books		
1.	1. Gerhard Ziegler, "Numerical Distance Protection", Siemens Publicis Corporate		
	Publishing, 2006		
2.	S.R. Bhide "Digital Power System Protection" PHI		

Sr. No.	Examination	Module
1	T-I	
2	T-II	
3	End Sem	1 to 7

Non linear Control System

Cours	se Code	Course Name	
PE-BTE809		Non linear Control System	
Course pre-requisites		Control System	
		Course Objectives	
<u>1</u> . Т			
		Course Outcomes	
1. U 2. U	Understand an Understand ma	tion of the course, students should be able to d apply concepts of linear algebra for system analysis. athematical models of various nonlinear systems. rmance of linear and nonlinear system and design controll	er
		Course Content	
Module No.		Details	Hrs.
1	common phy	systems: Introduction, behavior of non-linear system, resical non linearity- saturation, friction, backlash, dead zone, variable non- linearity.	04
2	portrait, Pha	e Analysis: Concept of phase plane, constructing phase se plane analysis of linear systems, Phase plane analysis of stems, Existence of limit cycles.	07
3	Fundamenta stability, line	als of Lyapunov theory: equilibrium points, concept of earization of nonlinear systems, Local stability, Lyapunov apunov's direct method, Stability and instability theorems.	08
4	System analy	vsis based on Lyapunov's direct method and Control Design upunov's direct method.	06
5	Describing I compensatio	Functions: Stability analysis and limit cycles, Linear n methods, General describing functions of common s, Relative stability.	05
6		nearization: feedback linearization and canonical form, nearization, Input- output linearization.	05
7 Control des 7 model, Lya		ign for nonlinear system: Control design using linearized punov method of control design, control design using earization and back stepping.	07
		Term Work	
Term wor	k shall comp	rise of	
	 Tutorials MCQ exa 	amination	
	mey on		
		Text Books	

Text Books

1. Slotine, J. E. & Weiping Li, Applied Nonlinear Control, Prentice-Hall, [1991]

2. Khalil, Hasan K., Nonlinear Systems, Macmillan Publishing, [1992]

- 1. Chi-Tsong Chen, "Linear Systems Theory and Design", Oxford University Press New York, 1999.
- 2. T. Kailath, "Linear Systems", Prentice-Hall, New Jersey, 1980, Science and

Business Media 2008.

- 3. Gilbert Strang, "Linear Algebra and its Application", Fourth Edition CENGAGE Learning
- 4. Ogata, K., Modern Control Engineering, Prentice-Hall, [2002]
- 5. Gopal, M., Modern Control System Theory, John Wiley Eastern Ltd. New Delhi, [1984]
- 6. Friedland, B., Control System Design, McGraw-Hill, [1986]
- 7. Ogata, K., State Space Analysis of Control Systems, Prentice-Hall, [1967]
- 8. Kuo, B. C., Automatic Control Systems, Prentice-Hall, [1987]

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	1 to 7

Robotics

	Robotics	
Cours	e Code Course Name	
OE-BTE801 Robotics		
Course pr	e-requisites	
	Course Objectives	
The objecti	ves of this course are	
	This course familiarizes students with the concepts and tech	niques
	in robot manipulator control.	
2.	Its main objective is to make students familiar with the	
	Kinematics and Dynamics involved.in robotic manipulator	
	used in automation industry.	
3.	To study and appreciate the need of control theory to control	l such a complex
	nonlinear.	
Upon succe	Course Outcomes essful completion of the course, students should be able TO	
opon succe	essiul completion of the course, students should be able 10	
1.	Appreciate the importance of robotic arm and its application	IS
	in automation industry.	
2.	Appreciate the importance of control system theory to control	lc
	such a complex nonlinear robotic arm.	
	Describe the kinematic and dynamic model of robotic arm.	
4.	Appreciate the importance of path, task and trajectory plann	ing
	Course Content	
Module	Details	Hrs.
No.	Introduction to Robotics	06
1	Automation and Robots, Classification, Application,	UU
1	Specification, Notations.	
	Direct Kinematics	06
2	Dot and Cross Products, Co-ordinate frames, Rot	,
	Homogeneous Co-ordinates, Link Coordinates, Arm Eq	uation
	(Three axis, Four axis and Five axis robots). Inverse Kinematics	06
3	General properties of solutions, Tool configuration, Inverse	
	Kinematics of Three axis, Four axis and Five axis robots.	
	Workspace Analysis	06
4	Workspace analysis of four axis and Five axis robots, Work	ζ.
	envelope, Workspace fixtures	
5	Trajectory Planning Trajectory Planning, Pick and Place operations, Continuous	06
5	motion, Interpolated motion, Straight-Line motion.	, paul
	Task Planning	06
6	Task level programming, Uncertainty, Configuration space	2,
	Gross motion Planning, Grasp planning, Fine-motion Planr	ning,

	Simulation of Planer motion, Source and goal scenes, Task planner simulation	
7	Robot Arm Dynamics Lagrange-Euler Formulation, Newton- Euler Formulation, Computational Algorithm, A two Link Manipulator Example, control Techniques applied to Robotic Arm.	06

Text Books

- 1. Robert Shilling, Fundamentals of Robotics-Analysis and Control, Prentice Hall of India.
- 2. Fu, Gonzales and Lee, Robotics, McGraw Hill.

- 1. J.J. Craig, Introduction to Robotics, Pearson Education.
- 2. Curtis D. Johnson, Process Control Instrumentation Technology, PHI publication.

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	1 to 7

Power Plant Engineering

		8 8	
Course Code OE-BTE802		Course Name	
		Power Plant Engineering	
Course pre-requisites			
•	•		
		Course Objectives	
The object	ives of this co		numion
	issues	an overview of power plants and the associated energy co	
	100000	Course Outcomes	
Upon succ	essful comple	tion of the course, students should be able to	
		the principles of operation for different power plants and	their
	economics	~ ~ ~	
Madula		Course Content	
Module No.		Details	Hrs.
	Coal based	I thermal power plants, basic Rankine cycle and its	06
1		ons, layout of modern coal power plant, super critical	
		C boilers, turbines, condensers, steam and heating rates	
2		s of thermal power plants, fuel and ash handling,	06
2	cogeneratio	stem, feed water treatment, binary cycles and	
		e and combined cycle power plants, Brayton cycle	06
		d optimization, components of gas turbine power	
3	plants, con		
	• •	er plants, Integrated Gasifier based Combined Cycle	
	(IGCC) Sy Basics of t	nuclear energy conversion, Layout and subsystems of	06
		wer plants, Boiling Water Reactor (BWR), Pressurized	VU
		actor (PWR), CANDU Reactor, Pressurized Heavy	
4		ctor (PHWR),	
		er Reactors (FBR), gas cooled and	
	-	al cooled reactors, safety measures for	
	nuclear por Hydroelect	1	06
5		tric power plants, classification, typical layout I, biogas and fuel cell power systems	UU
		onomic issues, power tariffs, load distribution	06
6		s, load curve, capital and operating cost of different	
	power plan	nts, pollution	
	control tec		0.6
7		vironmental issues including waste disposal options	06
	101 coal an	d nuclear plants.	

Text Books			
1. N	1. Nag P.K., Power Plant Engineering, 3rd ed., Tata McGraw Hill, 2008.		
	Reference Books		
 El Wakil M.M., Power Plant Technology, Tata McGraw Hill, 2010. Elliot T.C., Chen K and Swanekamp R.C., Power Plant Engineering, 2nd ed., McGraw Hill, 1998. 			
Sr. No.	Examination	Module	
1	T-I	1,2	
2	T-II	3,4	
3	End Sem	1 to 7	

Electrical Engineering Materials

Course Code Course Name			
OE-BTE803 Electrical Engineering Materials			
Course pr	e-requisites		
		Course Objecting	
The objecti	ves of this co	Course Objectives	
		e electrical and magnetic properties of material	
	2. Discuss	properties of dielectric material and semiconductors	
		Course Outcomes	
Upon succe	-	tion of the course, students should be able	matarial
		and properties of magnetic, dielectric and semiconductor	material
	2. Understa	and usage of different electrical engineering materials Course Content	
Module			
No.		Details	Hrs.
		Conduction I : Electronic and Ionic Conduction,	06
1	Conductivi	•	
		hm"s Law , Relaxation Time , Collision Time , Mean of an Electron , Electron Scattering	
		Conduction II: Resistivity of Metals, Effect of	06
2	Temperatu	•	
2	1 0	n Conductivity, Joule"s Law, High Conductivity And	
		Materials , Superconductivity and Applications	0.6
		n of Dielectrics : Polar and Non-Polar Dielectrics, cept of Polarization, Types of Polarization, Dielectric	06
		Internal Field in	
3		, Ferroelectric ,Spontaneous Polarization, Curie-Weiss	
		pelectric and Pyroelectric, Dielectric Loss, Breakdown	
	in Dielectr		0.6
		in Alternating Field : Dielectric Properties of Insulators ing Fields, Complex Dielectric Constant, Electronic	06
	Polarizatio		
4		ization, Frequency Dependence of Electronic	
		n, Dielectric Constant of Non-Polar Solids, Dipolar	
		, Loss Tangent	06
		Properties of Materials: Atomic Interpretation of ic, Paramagnetic, Anti-Ferromagnetic and	VO
5	-	etic Materials.	
Ferromagnetic Domain.			
		Core Materials for Rotating Machines, Transformers,	06
E		Magnets and Non Magnetic Steels, Nonmetallic	
6	U	Materials, Thin lets, Magnetic Materials for Ferromagnetic Tape	
		bry Devices	
7		actor Material Technology: Method for Material	06
1	Preparation	n, Purification and Doping, Introduction to Processes of	

Manufacturing	
Semiconductor Devices, Transistors, Integrated Circuits	
Monolithic Diodes, Integrated Resistors and Integrated	
Capacitor.	

Text Books

1. Dekkar, A.J., "Electrical Engineering Materials, Reprint Edition", 2009, Prentice Hall Publications Co.

Reference Books

1. Kasap S.O., "Principle of Electronic Materials and Devices", Second Edition, Tata McGraw-Hill.

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	1 to 7

Medical Electronics

Course Code Course Name			
OE-BTE804 Medical Electronics			
Course pre	Course pre-requisites Electronic circuit, Analog Circuit, Digital Electronics, Communication Engineering		ronics,
		Course Objectives	
The objectiv	ves of this co	purse are	
1.	Discuss bioe	electric potentials generated in human body	
2.	Understand	the basic principle, working and design of various auton	nated
	diagnostic e	quipments.	
3.	To study var	rious medical instrumentation systems, drug delivery sys	tems and
he	ealthmanage	ement systems.	
		Course Outcomes	
Upon succe	ssful comple	tion of the course, students should be able to	
1.	Understand	bioelectric potentials generated in human body	
2.	Use modern	n methodologies, multi-disciplinary skill set and knowled	ge while
w	orking on rea	al time projects that demand convergence of engineering, so	cience and
te	chnology		
		Course Content	
Module No.		Details	Hrs.
	Fundament	tals of Medical instrumentation	06
		of Bioelectric Potentials: Basic cell physiology,	
1	Physiological systems of body, Sources of biomedical signals.		
1		cal instrumentation system: Performance requirements,	
	intelligent		
	systems Biophysica	l signal contume nuccessing	06
		l signal capture, processing electrodes, Electrodes for ECG, EMG, Microelectrodes	00
2	-	al Transducers: Classification, Performance characteristics	
	• •	f transducers used in medical instrumentation.	
	¥ .	I Recorders	06
3		diograph, Vectorcardiograph, Phonocardiograph,	
		ephalograph, Electromayograph	
	Monitorin		06
	Patient mo	nitoring system: Cardiac Monitor, Central Monitors,	
4		ent of heart rate, temperature, respiratory rate	
-		y monitoring system: Arrhythmia monitors, ambulatory	
		instruments	
		nitoring instrument	0.6
~		naging system	06
5	-	iography, Magnetic Resonance imaging system,	
Ultasonic Imaging System		06	
6 Therapeutic Equipment		cemakers, Cardiac Defibrillators, Ventilators	VO
		, Telemedicine	06
7	•	multi channel telemetry systems, Implantable telemetry	vu

system, Essential parametes of telemedicine, telemedicine system, transmission of still and video images, Cyber medicine.

Text Books		
1. Medical Instrumentation, Application and Design by J.G. Webster, TMH.		
Reference Books		
1. Handbook of Biomedical Engineering by R.S. Khandpur, PHI		
2. Encyclopaedia of medical devices and instrumentation - J.G. Webster Vol I, II, III, IV (Joh		
Willey)		

Sr. No.	Examination	Module
1	T-I	1,2
2	T-II	3,4
3	End Sem	1 to 7

Image Processing

Course Code	Course Name	
OE=BTE805	Image Processing	
Course pre-requisites	Digital Signal Processing	

Course Objectives

The objectives of this course are

1. To develop an overview of the field of image processing

- 2. To learn the fundamental concepts of Digital Image Processing
- 3. To understand basic image enhancement and segmentation techniques
- 4. To illustrate Image Transform calculations mathematically and develop fast transform algorithm

5. To learn Image Compression and Decompression Techniques

Course Outcomes

Upon successful completion of the course, students should be able to

- 1. Understand the concept of Digital Image processing.
- 2. Explain image enhancement and Segmentation technique
- 3. Understand Digital Image compression and decompression techniques
- 4. Perform Binary Image Processing

Course Content		
Module No.	Details H	
1	Introduction: Background, Digital Image Representation, Fundamental Steps in Image Processing, Elements of a Digital Image Processing System	04
2	Digital Image Fundamentals: Elements of Visual Perception, A Simple Image Model, Sampling and Quantization, Some Basic Relationships between Pixels, Imagining Geometry. Image File Formats: BMP, TIFF and JPEG. Color Models (RGB, HSI, YUV)	06
3	Image Enhancement: Spatial Domain Methods, Frequency Domain Methods, Some Simple Intensity Transformations, Histogram Processing, Image Subtraction, Image Averaging, Background Smoothing Filters, Sharpening Filters, Low pass Filtering, High pass Filtering, Generation of Spatial Masks from Frequency Domain Specifications. Homomorphic Filtering	08
4	Image Segmentation and Representation:(i)Detection of Discontinuities, Edge Linking using Hough Transform, Thresholding, Region based Segmentation, Split and Merge Technique,(ii)Image Representation and Description,	06

	Chain Code, Polygonal, Representation,	
	Shape Number, Moments	
5	Binary Image Processing: Binary Morphological Operators, Hit-or-Miss Transformation, Boundary Extraction, Bagion Filling, Thinning and	06
	Boundary Extraction, Region Filling, Thinning and Thickening,	
6	Image Transform: (i) Introduction to the Fourier Transform, The Discrete Fourier Transform, Some Properties of the Two-Dimensional Fourier Transform Fast Fourier Transform(FFT), (ii) Discrete Hadamard Transform(DHT), Fast Hadamard Transform(FHT), Discrete Cosine Transform(DCT), Discrete Wavelet Transform(DWT),	06
7	 Image Compression: Fundamentals – Coding Redundancy, Interpixel Redundancy, Psycho visual Redundancy, Fidelity Criteria. Image Compression Models – The Source Encoder and Decoder, Lossless Compression Techniques : Run Length Coding, Arithmetic Coding, Huffman Coding, Differential PCM Lossy Compression Techniques: Improved Gray Scale Quantization, Vector Quantization, JPEG, MPEG-1. 	06

	Text Books			
1.	 Rafel C. Gonzalez and Richard E. Woods, "Digital Image Processing", Pearson Education Asia, Third Edition, 2009, 			
Reference Books				
1.	S. Jayaraman, E. Esakkirajan and T. Veerkumar, "Digital Image			
	Processing" Tata McGraw Hill Education Private Ltd, 2009,			
2.	Anil K. Jain, "Fundamentals and Digital Image Processing", Prentice Hall			

of India Private Ltd, Third Edition
No. Examination Mod

Sr. No.	Examination	Module
1	T-I	1, 2, Part of 3
2	T-II	Part of 3, 4, Part of
		5
3	End Sem	1 to 7

Value Added Courses

1. PLC (VA-BTE03) Course Objective:

- 1. Discuss the purpose, functions, and operations of a PLC
- 2. Explain basic components of the PLC and how they function

Course Outcome: Students will be able to

- 1. Generate and print out a ladder logic report using PLC software
- 2. Create a PLC project using PLC
- 3. Configure the I/O for a PLC project using PLC

Course content: 1. Introductions to the purpose, functions, and operations of the PLC, Identification of various components of the PLC, 2. Introduction to PLC ladder logic and basic programming concepts, Establishing communications with the PLC, 3. Definitions of conditional inputs and outputs, Electrical continuity versus logical continuity, 4. PLC timer and counter concepts and programming applications, 5. Programming applications using sequencers.

2. Soft Computing II ETAP and WAMS (VA-BTE06)

Course Objective:

- 1. Introduce ETAP software
- 2. Discuss the synchro phasor measurement techniques in a Wide Area Control through the basic building blocks of GPS satellite synchronized clocks, the architecture of the Phasor Measurement Units (PMUs), and The communications equipment.

Course Outcome: Students will be able to

- 1. Use ETAP as an analysis platform for the designing, simulating, operating and automation of generation and distribution of power systems.
- 2. Understand the synchro phasor measurement techniques in a Wide Area Control

Course content: 1. Build power systems and simulate the power, current and voltage flow, Single Line diagram creation and analysis, run and Analyze AC power circuits, 2. Run load flow analysis on one line diagram, run Short Circuit analysis.

3. Introduction to Synchro Phasor & WAMS Technologies, Synchro Phasor needs and benefits for Operations, 4. Planning and Control Vision for Synchro Phasor & Online Stability Solutions Fundamental building blocks for WAMS and Synchro Phasor Platform Architecture, 5. PMU standard and communication

Project Stage II PR-BTE801

Course Code	Course Name
PR-BTE801	Project Stage-II
Course Pre-Requisites	Course pre-requisites: Recommended – all courses till semester VII

Course Objectives

Objectives of the course is:

- 1. Apply knowledge of principles of engineering for a developing society
- 2. To be able to do literature survey and be able to put it ethically towards solving an engineering problem
- 3. To develop an ability to empathize and formulate problem and analyze it.

Course Outcomes

At the end of the course the student will be able to:

- 1. Application of basic principles, modern techniques and/or IT tools, experimental/lab data for analysis and solving of the identified problem
- 2. Derive logical conclusions based on technical/economic study carried out.
- 3. Communicate the findings through written reports, presentations and/or research publications

Course Content		
Module No.	Description	Hrs.
1	Student shall study the topic of project work in terms of data collection, analysis, and inferencing. There would be two or more evaluation throughout the semester by committee of Faculty members.	2+14(Self study)